

## Features

- Exceeds Requirements of EIA-485 Standard
- Hot Plug Circuitry - Tx and Rx Outputs Remain Three-State During Power-up/Power-down
- Supply voltage: 3.0V ~ 5.5V
- Data Rate: 32Mbps or 500Kbps
- Up to 256 Nodes on a Bus (1/8 unit load)
- Full Fail-safe Receiver (Open, Short, Terminated)
- H/F control to support Half and Full Duplex RS485
- Polarity Control to Correct for Bus Reversal through RXP/TXP Pins
- Bus-Pin Protection:
  - ±12 kV IEC61000-4-2 Contact Discharge
  - ±15 kV IEC61000-4-2 Air Discharge
  - ±2 kV IEC61000-4-4 Fast Transient Burst
- -40°C to 125°C Operation Temperature Range

## Description

The TPT4089 is IEC61000 ESD protected, 5V transceivers that meet the RS-485 and RS-422 standards for Half and Full Duplex communication.

The TPT4089 features a fail-safe receiver, which support the output of the receiver to be logic high when the differential input (bus pin A/B) of the receiver is open, short or idle when RXP=0V.

Transmitters in this family deliver exceptional differential output voltages into the RS-485 required 54Ω load. The 10Mbps devices have very low bus currents so they present a true “1/8 unit load” to the RS-485 bus. This allows up to 256 transceivers on the network without using repeaters. Receiver (Rx) inputs feature a “Full Fail-Safe” design, which ensures a logic high Rx output if Rx inputs are floating, shorted, or on a terminated but undriven bus. The TPT48x is characterized from -40°C to 125°C.

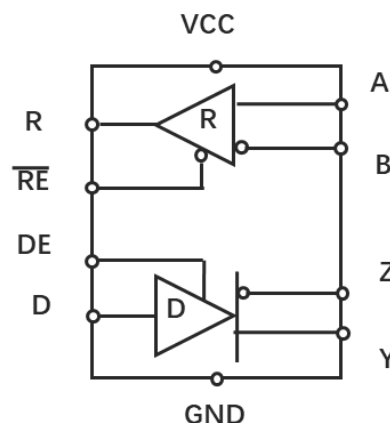
## Applications

- Home Appliance
- Motor Drives
- Industrial Control
- Communication Infrastructure

## Device Table

Part	Duplex	Enable	Data Rate	Package
TPT4089	Half or Full	Yes	32Mbps or 500Kbps	SOP14

## Simplified Schematic



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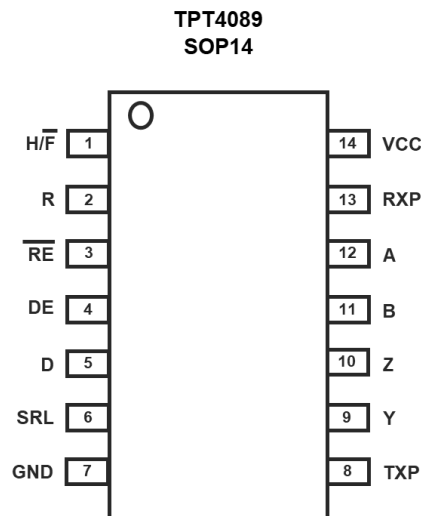
## Revision History

Date	Revision	Notes
2020/12/18	Rev. Pre.0	Definition Version Pre.0
2022/4/22	Rev. A0	Released version

## Order Information

Order Number	Operating Temperature Range	Package	Marking Information	MSL	Transport Media, Quantity
TPT4089-SO2R	-40 to 125°C	SOP14	T4089	3	Tape and Reel, 2,500

## Pin Configuration and Functions



Pin No.	Pin Name	I/O	Description
1	H/F	Digital input	Half-/Full-Duplex Select Input. Connect H/F to VCC for half-duplex mode; connect H/F to GND or leave unconnected for full-duplex mode
2	R	Digital output	Receiver Output
3	/RE	Digital input	Receiver Output Enable
4	DE	Digital input	Driver Output Enable
5	D	Digital input	Driver Input
6	SRL	Digital input	Slew-Rate Limit Selector Input. Connect SRL to ground for 32Mbps data rate; connect SRL to VCC or Leave SRL unconnected for 500kbps data rate
7	GND	Ground	Ground
8	TXP	Digital input	Transmitter Phase. Connect TXP to ground or leave TXP unconnected for normal transmitter phase/polarity. Connect TXP to VCC to invert the transmitter phase/polarity
9	Y	Bus output	Noninverting Driver Output
10	Z	Bus output	Inverting Driver Output
11	B	Bus input	Inverting Receiver Input
12	A	Bus input	Noninverting Receiver Input
13	RXP	Digital input	Receiver Phase. Connect RXP to GND or leave RXP unconnected for normal transmitter phase/polarity. Connect RXP to VCC to invert receiver phase/polarity
14	VCC	Power	Power Supply

## Functional Table

### Functional Table of TPT4089

#### Driver Function Table

Input	Enable	Output	Output	Description
D	DE	A	B	
H	H	H	L	Actively drives bus High
L	H	L	H	Actively drives bus Low
X	L	Z	Z	Driver disabled
X	OPEN	Z	Z	Driver disabled by default
Open	H	H	L	Actively drives bus High by default

X = don't care

Z = high impedance

#### Receiver Function Table

Input	Input	Output	Description
A-B	/RE	R	
>-50mV	L	H	Receive valid bus High
-200mV<Input<-50mV	L	?	Indeterminate bus state
<-200mV	L	L	Receive valid bus Low
X	H	Z	Receiver disabled
X	OPEN	Z	Receiver disabled in default
Open	L	H	Fail-safe high output
Short	L	H	Fail-safe high output
Idle (Terminated)	L	H	Fail-safe high output

X = don't care

Z = high impedance

## Absolute Maximum Ratings

Parameters	Rating
VCC to GND	-0.3V to +7V
Voltage at Logic pin: D, DE, /RE, R	-0.3V to VCC + 0.3V
Voltage at Bus pin: A, B, Y, Z <sup>(1)</sup>	-15V to +15V
Operating Temperature Range	-40°C to 125°C
Storage Temperature Range	-65°C to 150°C
Maximum Junction Temperature	150°C
Lead Temperature (Soldering, 10 sec)	260°C

(1) Support ±15V in receiver mode, and -8 ~+13V in driver mode

(2) Stresses beyond the *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*.

## Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
VCC	Supply voltage	3.0		5.5	V
V <sub>I</sub>	Input voltage at any bus terminal <sup>(1)</sup>	-7		12	V
V <sub>IH</sub>	High-level input voltage (driver, driver enable, and receiver enable inputs)	2		VCC	V
V <sub>IL</sub>	Low-level input voltage (driver, driver enable, and receiver enable inputs)	0		0.8	V
V <sub>ID</sub>	Differential input voltage	-7		12	V
R <sub>L</sub>	Differential load resistance	54			Ω
T <sub>A</sub>	Operating ambient temperature	-40		125	°C
T <sub>J</sub>	Junction temperature	-40		150	°C

(1) The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

## ESD Rating

		Value	Unit
IEC-61000-4-2, Contact Discharge	Bus Pin	±12	kV
IEC-61000-4-2, Air-Gap Discharge	Bus Pin	±15	kV
HBM, per ANSI/ESDA/JEDEC JS-001 / ANSI/ESD STM5.5.1	Bus Pin	±18	kV
	All Pin Except Bus Pin	±4	kV
CDM, per ANSI/ESDA/JEDEC JS-002	All Pin	±1.5	kV

## Thermal Information

Package Type	θ <sub>JA</sub>	θ <sub>JC</sub>	Unit
14-Pin SOIC	120	36	°C/W

## Electrical Characteristics

All test condition is  $V_{CC} = 3.3V \sim 5.0V$ ,  $T_A = -40 \sim +125^{\circ}C$ , unless otherwise noted.

Symbol	Parameter	Test Conditions		Min	MAX	Unit
V <sub>OD</sub>	Driver differential output voltage magnitude	R <sub>L</sub> = 54 Ω, V <sub>CC</sub> =3.3V		1.5	2.2	V
		R <sub>L</sub> = 54 Ω, V <sub>CC</sub> =5.0V		2.0	3.3	V
		R <sub>L</sub> = 100 Ω, V <sub>CC</sub> = 3.3V		1.5	2.6	V
		R <sub>L</sub> = 100 Ω, V <sub>CC</sub> = 5.0V		3.0	3.9	V
Δ V <sub>OD</sub>	Change in magnitude of driver differential output voltage			-50	50	mV
V <sub>OC(SS)</sub>	Steady-state common-mode output voltage	Center of two 27-Ω load resistors		1	V <sub>CC</sub> /2	V
ΔV <sub>OC</sub>	Change in differential driver output common-mode voltage			-200	200	mV
C <sub>OD</sub>	Differential output capacitance <sup>[1]</sup>			15		pF
V <sub>IT+</sub>	Positive-going receiver differential input voltage threshold			-110		-50 mV
V <sub>IT-</sub>	Negative-going receiver differential input voltage threshold			-200	-130	mV
V <sub>HYS</sub>	Receiver differential input voltage threshold hysteresis (V <sub>IT+</sub> - V <sub>IT-</sub> ) <sup>[1]</sup>			50		mV
V <sub>OH</sub>	Receiver high-level output voltage	V <sub>CC</sub> = 3.3 V, I <sub>OH</sub> = -8 mA		2.6	3.0	V
		V <sub>CC</sub> = 5 V, I <sub>OH</sub> = -8 mA		4.1	4.8	
V <sub>OL</sub>	Receiver low-level output voltage	V <sub>CC</sub> = 3.3 V, I <sub>OH</sub> = -8 mA		0.19	0.4	V
		V <sub>CC</sub> = 5 V, I <sub>OH</sub> = -8 mA		0.02	0.4	
V <sub>IH</sub>	Input High Logic Level	D, DE, /RE, TXP, RXP, SRL, H/F		2.0		V
V <sub>IL</sub>	Input Low Logic Level	D, DE, /RE, TXP, RXP, SRL, H/F		0.8		V
I <sub>IN</sub>	Driver input, driver enable, and receiver enable input current	D, DE, /RE		-5	5	μA
I <sub>IN</sub>	Driver input, driver enable, and receiver enable input current	TXP, RXP, H/F		-1	40	μA
I <sub>IN</sub>	Driver input, driver enable, and receiver enable input current	SRL		-15	15	μA
I <sub>OZ</sub>	Driver output high-Z current	V <sub>O</sub> = -7V		-100	0	μA
		V <sub>O</sub> = 12V		0	125	
I <sub>OZ</sub>	Receiver high-Z current	V <sub>O</sub> = 0 V or V <sub>CC</sub>		-1	1	μA
I <sub>OS</sub>	Driver short-circuit output current	V <sub>Y</sub> , V <sub>Z</sub> = -7V ~ 12V		-250	250	mA
		R=0V or V <sub>CC</sub>		-180	180	
I <sub>IAB</sub>	Bus input current (disabled driver)	DE = 0 V, RE=V <sub>CC</sub>	V <sub>I</sub> = 12 V,	55	125	μA
			V <sub>I</sub> = -7 V,	-100	-50	μA
I <sub>CC</sub>	Supply current (quiescent), 32Mbps	Driver and Receiver enabled	DE=V <sub>CC</sub> , RE = GND, No load	1200	2500	μA
		Driver enabled, receiver disabled	DE=V <sub>CC</sub> , RE = V <sub>CC</sub> , No load	1200	2500	μA
		Driver disabled, receiver enabled	DE=GND, RE = GND, No load	1000	2200	μA
		Driver and receiver disabled	DE=GND, RE = V <sub>CC</sub> , No load	-5	5	μA

**3.3V~5.0V Full Duplex RS-485 Transceivers with polarity control**

I <sub>CC</sub>	Supply current (quiescent), 500Kbps	Driver and Receiver enabled	DE=VCC, RE = GND, No load	1000	μA
		Driver enabled, receiver disabled	DE=VCC, RE = VCC, No load	400 1000	μA
		Driver disabled, receiver enabled	DE=GND, RE = GND, No load	400 1000	μA
		Driver and receiver disabled	DE=GND, RE = VCC, No load	-5 5	μA

Note:

[1]. Parameters are provided by lab bench test and design simulation

**Switching Characteristics, VCC= 5.0V — TPT4089 in 32Mbps**

Parameter		Conditions	Min	Typ	Max	Units	
Driver							
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times <sup>[1]</sup>	RL = 54 Ω, CL=50pF	See Figure 2		5		ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay				19	30	
t <sub>SK(P)</sub>	Driver pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>   <sup>[1]</sup>				1		
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Driver disable time	/RE=0 or VCC	See Figure 3		37	50	ns
t <sub>PZH</sub> , t <sub>PZL</sub>	Driver enable time	Receiver enabled			21	40	ns
		Receiver disabled			1760	2500	
Receiver							
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times <sup>[1]</sup>				4		ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Receiver propagation delay time				36	45	ns
t <sub>SK(P)</sub>	Receiver pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>				4		
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Receiver disable time	DE=0 or VCC	See Figure 6		15	25	ns
t <sub>PZH</sub> , t <sub>PZL</sub>	Receiver enable time	Driver enabled			14	25	ns
		Driver disabled			1750	2500	

Note:

[1]. Parameters are provided by lab bench test and design simulation

**Switching Characteristics, VCC=3.3V — TPT4089 in 32Mbps**

Parameter	Conditions	Min	Typ	Max	Units
<b>Driver</b>					
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times <sup>[1]</sup>		6		ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay		22	30	



**3.3V~5.0V Full Duplex RS-485 Transceivers with polarity control**

Parameter		Conditions		Min	Typ	Max	Units
tsk(P)	Driver pulse skew,  tPHL – tPLH				1		
tPHZ, tPLZ	Driver disable time	/RE=0 or VCC	See Figure 3		40	55	ns
tPZH, tPZL	Driver enable time	Receiver enabled			30	50	ns
		Receiver disabled			2560	4000	
Receiver							
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times <sup>[1]</sup>				4		ns
tPHL, tPLH	Receiver propagation delay time				47	60	ns
tsk(P)	Receiver pulse skew,  tPHL – tPLH				6		
tPHZ, tPLZ	Receiver disable time	DE=0 or VCC	See Figure 6		21	30	ns
tPZH, tPZL	Receiver enable time	Driver enabled			17	30	ns
		Driver disabled			2550	4000	

Note:

[1]. Parameters are provided by lab bench test and design simulation

**Switching Characteristics, VCC= 5.0V — TPT4089 in 500Kbps**

Parameter		Conditions		Min	Typ	Max	Units
Driver							
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times <sup>[1]</sup>	RL = 54 Ω, CL=50pF	See Figure 2		470		ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay				450	600	
t <sub>SK(P)</sub>	Driver pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>				6		
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Driver disable time	/RE=0 or VCC	See Figure 3		61	100	ns
t <sub>PZH</sub> , t <sub>PZL</sub>	Driver enable time	Receiver enabled			216	500	ns
		Receiver disabled			1960	4000	
Receiver							
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times <sup>[1]</sup>				15		ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Receiver propagation delay time				100	150	ns
t <sub>SK(P)</sub>	Receiver pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>				5		
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Receiver disable time	DE=0 or VCC	See Figure 6		20	50	ns
t <sub>PZL</sub> , t <sub>PZH</sub>	Receiver enable time	Driver enabled			25	50	ns
		Driver disabled			1760	4000	

Note:

[1]. Parameters are provided by lab bench test and design simulation

**Switching Characteristics, VCC=3.3V — TPT4089 in 500Kbps**

Parameter		Conditions	Min	Typ	Max	Units	
Driver							
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times <sup>[1]</sup>	RL = 54 Ω, CL=50pF	See Figure 2		460	ns	
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay				460		700
tsk(P)	Driver pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>				4		
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Driver disable time	/RE=0 or VCC	See Figure 3		67	200	ns
t <sub>PZH</sub> , t <sub>PZL</sub>	Driver enable time	Receiver enabled			350	1000	ns
		Receiver disabled			2870	4000	
Receiver							
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times <sup>[1]</sup>				20		ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Receiver propagation delay time				115	200	ns
tsk(P)	Receiver pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>				8		
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Receiver disable time	DE=0 or VCC	See Figure 6		21	40	ns
t <sub>PZL</sub> , t <sub>PZH</sub>	Receiver enable time	Driver enabled			33	50	ns
		Driver disabled			2560	4000	

Note:

[1]. Parameters are provided by lab bench test and design simulation

## Test Circuits and Waveforms

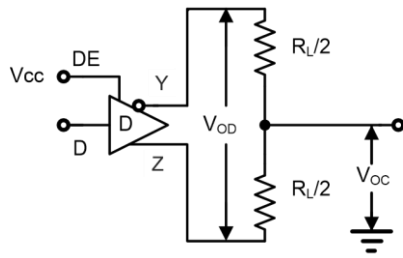


Figure 1A. VOD and VOC

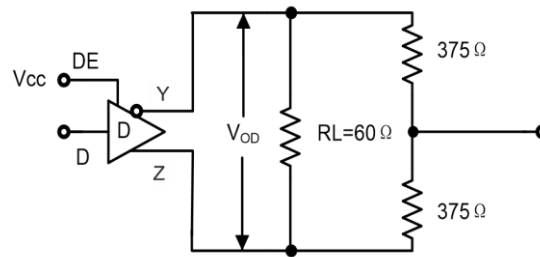


Figure 1B. VOD with Common Mode Load

Figure 1. DC Driver Test Circuits

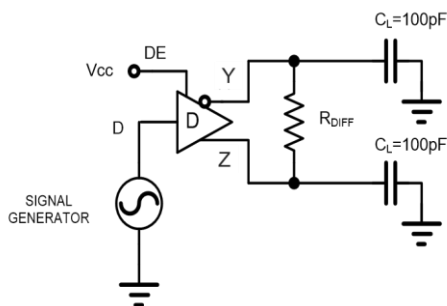


Figure 2A. Test Circuit

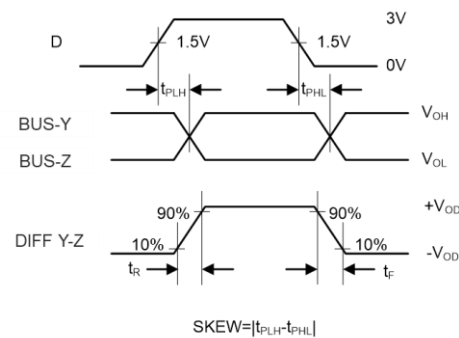


Figure 2B. Measurement Points

Figure 2. Driver Propagation Delay and Differential Transition Times

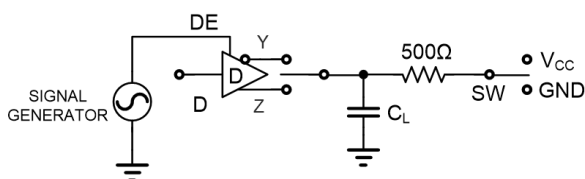


Figure 3A. Test Circuit

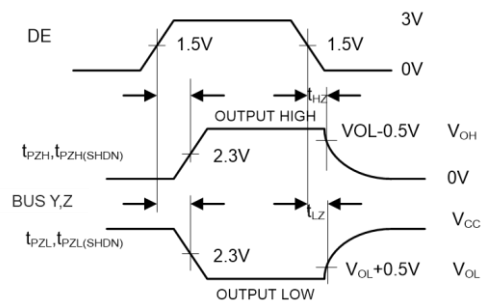


Figure 3B. Measurement Points

PARAMETER	OUTPUT	RE	DI	SW	CL (pF)
tPHZ	Y/Z	X	1/0	GND	15
tPLZ	Y/Z	X	0/1	VCC	15
tPZH	Y/Z	0	1/0	GND	100
tPZL	Y/Z	0	0/1	VCC	100
tPZH(SHDN)	Y/Z	1	1/0	GND	100
tPZL(SHDN)	Y/Z	1	0/1	VCC	100

Figure 3. Driver Enable and Disable Times

## Test Circuits and Waveforms (continue)

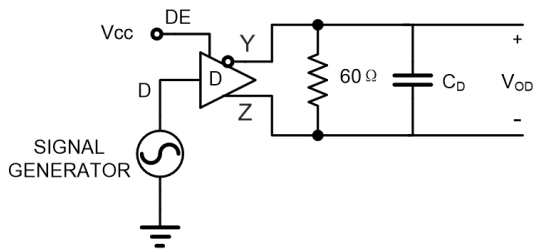


Figure 4A. Test Circuit

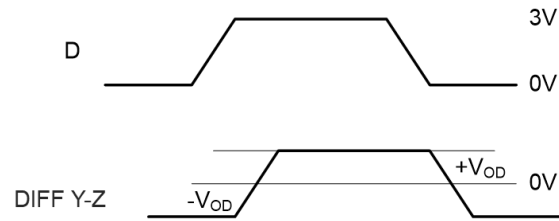


Figure 4B. Measurement Points

Figure 4. Driver Data rate

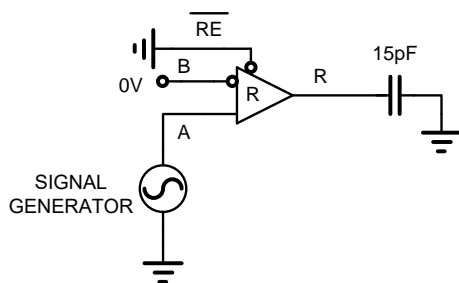


Figure 5A. Test Circuit

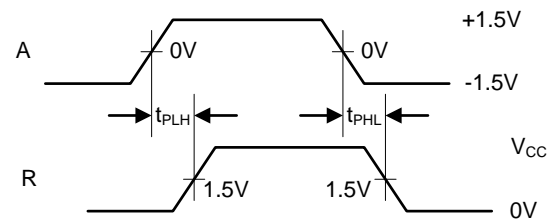
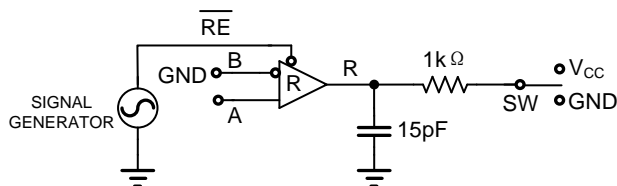


Figure 5B. Measurement Points

Figure 5. Receiver Propagation Delay and Data rate



PARAMETER	DE	A	SW
tPHZ	1	+1.5V	GND
tPLZ	1	-1.5V	VCC
tPZH	1	+1.5V	GND
tPZL	1	-1.5V	VCC
tPZH(SHDN)	0	+1.5V	GND
tPZL(SHDN)	0	-1.5V	VCC

Figure 6A. Test Circuit

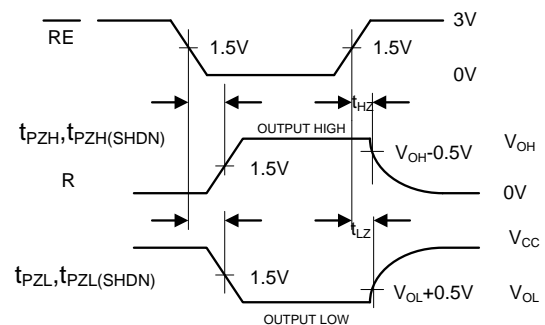
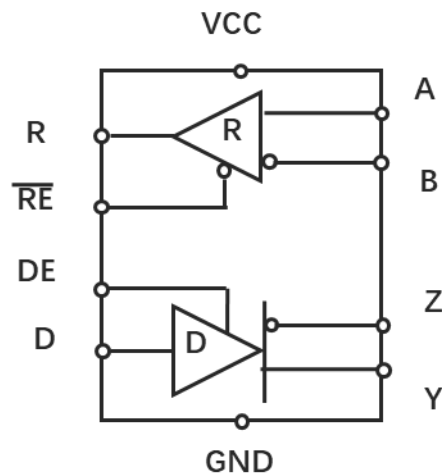


Figure 6B. Measurement Points

Figure 6. Receiver Enable and Disable Times

## Function Block diagram:



## Theory of Operation

### General description

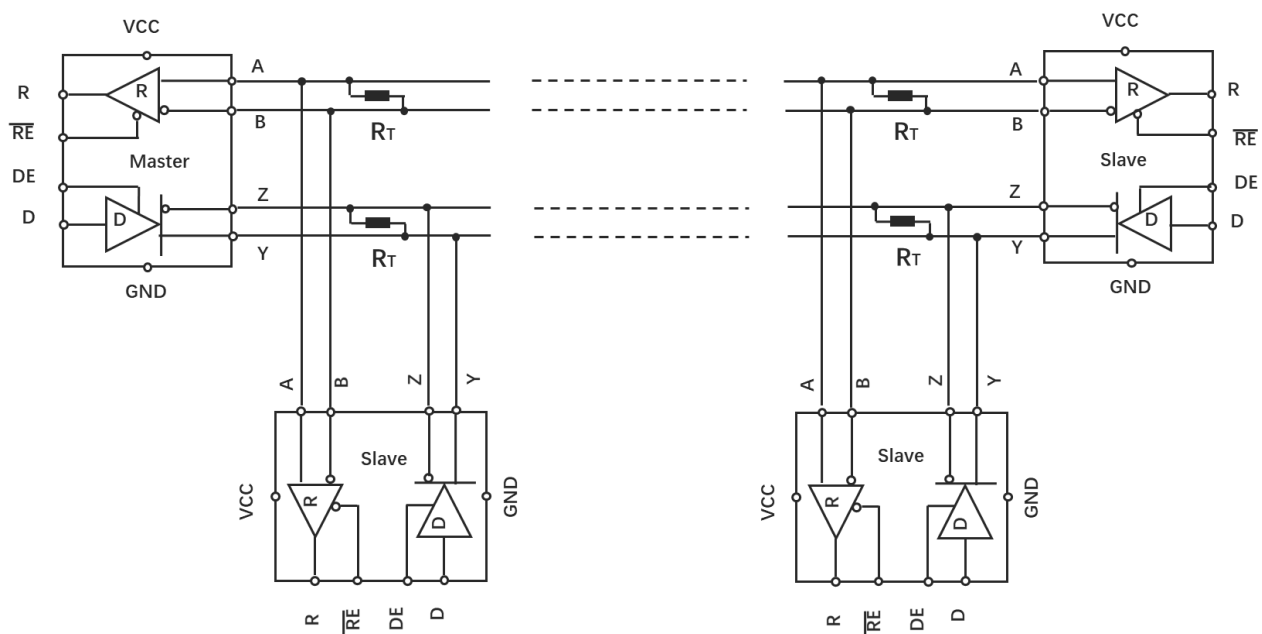
The TPT4089 is a RS-485/RS-422 transceivers with robust HBM and IEC 61000 ESD protection. The device build in fail-safe circuit, when the receiver input is open or shorted, or idle mode, it will generate a logic-high receiver output. The TPT4089 supports hot-swap function allowing line insertion to avoid wrong data transmission, and optimizes the drivers slew-rate to minimize EMI and reduce reflections caused by different terminated cables, then support the error-free data communication at 500Kbps data rate. As the driver slew rates is not limited, so the TPT4089 can support the high communication speed up to 32Mbps. Use the SRL pin ( Slew-Rate Limit) to config the device in different data rate communication, connecting SRL to ground for 32Mbps data rate; Connecting SRL to VCC or Leave SRL unconnected for 500kbps data rate.

The TPT4089 use a selector pin (H/F) high or low to select the status between half- and full-duplex communication.

The TPT4089 operates from a single +3.3V to 5.0V power supply, the driver is designed with output short-circuit current limitation, together with thermal-shutdown circuitry to protect drivers in the status of excessive power dissipation. In active mode, the thermal-shutdown circuitry places the driver outputs into a high-impedance state.

In the typical RS485 communication, twisted-pair lines are connected backward in the network. The TPT4089 has two pins that invert the phase of the driver and the receiver to correct this problem. For normal operation, drive TXP and RXP low, connect them to ground, or leave them unconnected with internal pulldown. Connect TXP as High to invert the driver phase. To invert the receiver phase, then the RXP should connect it to VCC, and note that the receiver threshold is positive in this status.

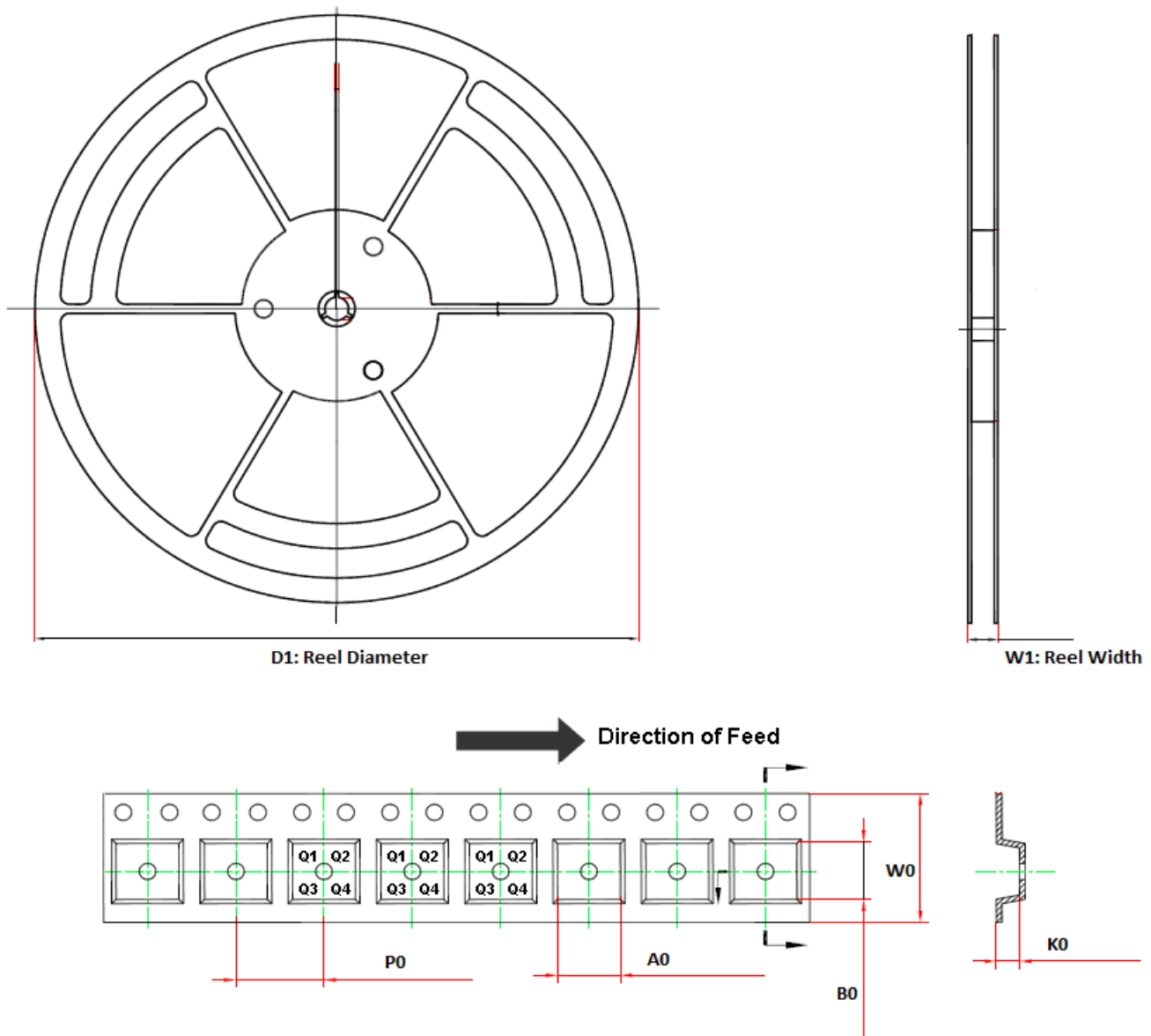
## Application Information



**Figure 7. Typical RS485 communication network**

The TPT4089 transceiver is designed for bidirectional RS485/422 data communications on multipoint bus transmission lines. Figures 7 shows typical network applications circuit to support up to 256 nodes. To minimize line reflections, terminate the line at both ends in its characteristic impedance, one 120ohm load in master side, and another 120ohm load in the end of slave side, and limit stub lengths off the main line as short as possible. TPT4089 is more tolerant of imperfect termination for 500Kbps low data rate and 32Mbps high data rate.

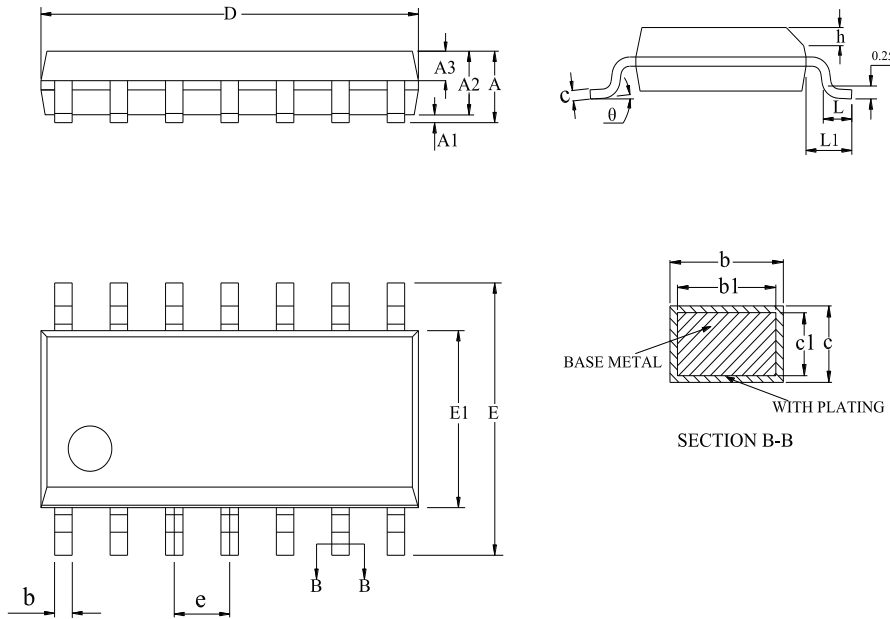
## Tape and Reel Information



Order Number	Package	D1	W1	A0	B0	K0	P0	W0	Pin1 Quadrant
TPT4089-SO2R	14-Pin SOP	330.0	21.6	6.5	9.0	2.1	8.0	16.0	Q1

## Package Outline Dimensions

### SOP-14



SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	—	—	1.75
A1	0.05	—	0.225
A2	1.30	1.40	1.50
A3	0.60	0.65	0.70
b	0.39	—	0.47
b1	0.38	0.41	0.44
c	0.20	—	0.24
c1	0.19	0.20	0.21
D	8.55	8.65	8.75
E	5.80	6.00	6.20
E1	3.80	3.90	4.00
e	1.27BSC		
h	0.25	—	0.50
L	0.50	—	0.80
L1	1.05REF		
$\theta$	0	—	8°



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