

## Features

- Meet the ISO 11898 Standard
- Support CAN FD and Data Rates up to 5 Mbps
- Typical Loop Delay: 110 ns
- 5-V Power Supply, 3.0-V~5.5-V IO Interface
- Receiver Common-Mode Input Voltage:  $\pm 30$  V
- Bus Fault Protection:  $\pm 42$  V
- Up to 110 Nodes in CAN Network
- Junction Temperatures from  $-40^{\circ}\text{C}$  to  $150^{\circ}\text{C}$
- Latch-up Performance Exceeds 500 mA
- BUS Pin ESD Protection :
  - $\pm 8$ -kV Human-Body Model
  - $\pm 1.5$ -kV Charged-Device Model

## Applications

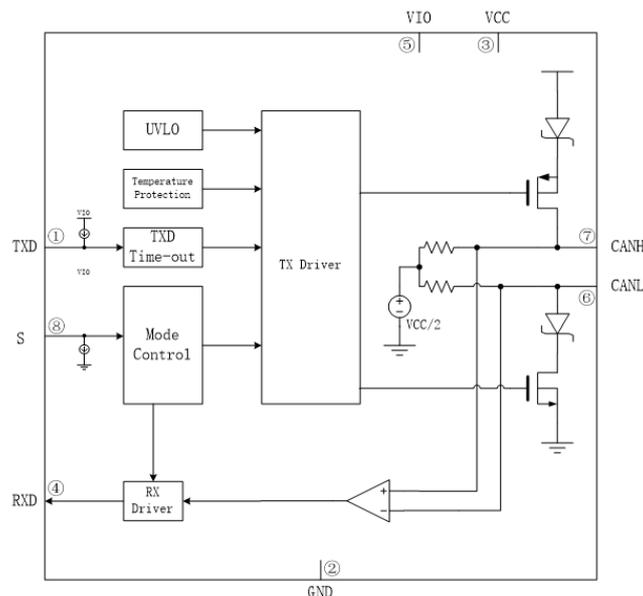
- All Devices Support Highly Loaded CAN Networks
- Field Industrial Automation, Sensors, and Drive Systems
- Building, Security Control Systems
- Energy Storage Systems
- Telecom Base Station Status and Control

## Description

The TPT1051V is a CAN transceiver that meets the ISO11898 high-speed CAN (Controller Area Network) physical layer standard. The device is designed to be used in CAN FD networks up to 5 Mbps with enhanced timing margin higher data rates in long and highly loaded networks. As designed, the device features cross-wire, overvoltage, loss of ground protection from  $-42$  V to  $+42$  V, overtemperature shutdown, and a  $-30$ -V to  $+30$ -V common-mode range. The TPT1051V has a secondary power supply input for the I/O level, shifting the input pin thresholds and RXD output level, and the device comes with silent mode which is also commonly referred to as listen-only mode. It includes many protection features to enhance the device and network robustness.

The TPT1051V is available in SOP8 and DFN3x3-8 packages and is characterized from  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .

## Typical Application Circuit



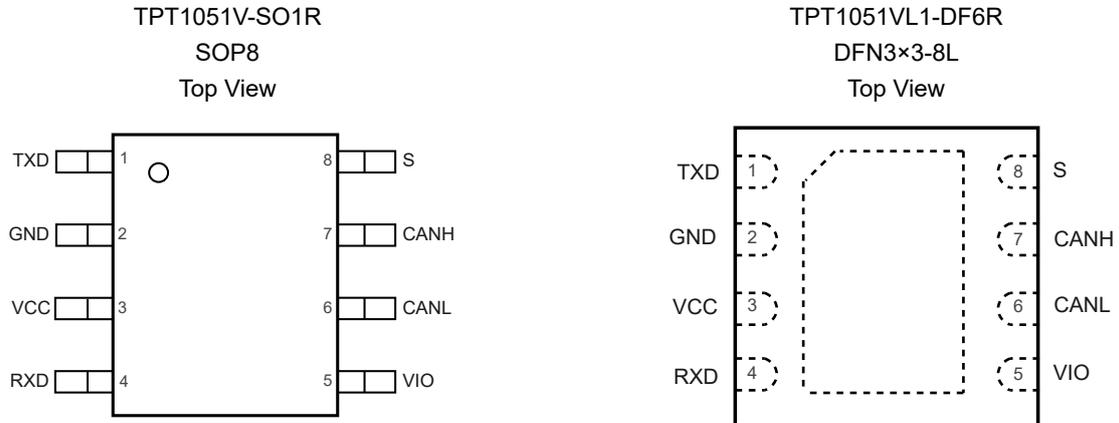
## Table of Contents

<b>Features</b> .....	<b>1</b>
<b>Applications</b> .....	<b>1</b>
<b>Description</b> .....	<b>1</b>
<b>Typical Application Circuit</b> .....	<b>1</b>
<b>Revision History</b> .....	<b>3</b>
<b>Pin Configuration and Functions</b> .....	<b>4</b>
<b>Specifications</b> .....	<b>5</b>
Absolute Maximum Ratings <sup>(1)</sup> .....	5
Recommended Operating Conditions.....	5
ESD, Electrostatic Discharge Protection.....	5
Thermal Information.....	6
Power Consumption.....	6
Electrical Characteristics.....	7
AC Timing Requirements.....	10
<b>Detailed Description</b> .....	<b>12</b>
Overview.....	12
Functional Block Diagram.....	12
Feature Description.....	13
<b>Tape and Reel Information</b> .....	<b>14</b>
<b>Package Outline Dimensions</b> .....	<b>15</b>
SOP8.....	15
DFN3×3-8.....	16
<b>Order Information</b> .....	<b>17</b>
<b>IMPORTANT NOTICE AND DISCLAIMER</b> .....	<b>18</b>

## Revision History

Date	Revision	Notes
2020-02-18	Rev. Pre.0	Initial version.
2020-04-24	Rev. Pre.1	Updated the ESD level.
2020-05-18	Rev. Pre.2	Updated the electrical parameters.
2020-06-17	Rev. Pre.3	Added the DFN3×3-8L package.
2020-06-30	Rev.0	Released version.
2020-12-25	Rev.A.0	Updated the notes for Absolute Maximum Ratings.
2022-07-25	Rev.A.1	Updated the POD of SOP8 and DFN3×3-8.
2022-09-28	Rev.A.2	Updated the package drawing of DFN3×3-8.
2024-12-24	Rev.A.3	Updated to a new datasheet format. Updated the POD.

## Pin Configuration and Functions



**Table 1. Pin Functions: TPT1051V**

Pin No.	Name	I/O	Description
1	TXD	I	CAN transmit data input (low for dominant and high for recessive bus states).
2	GND	GND	Ground.
3	VCC	POWER	Transceiver 5-V supply voltage.
4	RXD	O	CAN receive data output (low for dominant and high for recessive bus states).
5	VIO	POWER	Transceiver I/O level shifting supply voltage (devices with "V" suffix only).
6	CANL	BUS I/O	Low-level CAN bus input/output line.
7	CANH	BUS I/O	High-level CAN bus input/output line.
8	S	I	Silent mode control input (active high).

## Specifications

### Absolute Maximum Ratings <sup>(1)</sup>

Parameter		Min	Max	Unit
V <sub>CC</sub>	5-V Bus Supply Voltage Range	-0.3	7	V
V <sub>IO</sub>	I/O Level-Shifting Voltage Range	-0.3	7	V
V <sub>BUS</sub>	CAN Bus I/O Voltage Range (CANH, CANL)	-42	42	V
V <sub>(Logic_Input)</sub>	Logic Input Terminal Voltage Range (TXD, S)	-0.3	7	V
V <sub>(Logic_Output)</sub>	Logic Output Terminal Voltage Range (RXD)	-0.3	7	V
IO (RXD)	RXD (Receiver) Output Current	-8	8	mA
T <sub>J</sub>	Maximum Operating Junction Temperature	-40	150	°C
T <sub>STG</sub>	Storage Temperature Range	-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

(2) This data was taken with the JEDEC low effective thermal conductivity test board.

(3) This data was taken with the JEDEC standard multilayer test boards.

### Recommended Operating Conditions

Parameter		Min	Typ	Max	Unit
V <sub>I/O</sub>	Input/Output Voltage SCL1, SDA1, SCL2, SDA2	3.0		5.5	V
V <sub>CC</sub>	Power Supply	4.5		5.5	V
I <sub>OH (RXD)</sub>	RXD Terminal High-Level Output Current	-2			mA
I <sub>OL (RXD)</sub>	RXD Terminal Low-Level Output Current			2	mA
T <sub>A</sub>	Operating Ambient Temperature	-40		125	°C

### ESD, Electrostatic Discharge Protection

Symbol	Parameter	Condition	Minimum Level	Unit
HBM	Human Body Model ESD	ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup> , bus pin	±8	kV
		ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup> , all other pins except for bus pin	±8	kV
CDM	Charged Device Model ESD	ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	±1.5	kV
LU	Latch-Up	JESD78	±500	mA

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### Thermal Information

Package Type	$\theta_{JA}$	$\theta_{JC}$	Unit
SOP8	148	48	°C/W
DFN3×3-8	52	23	°C/W

### Power Consumption

Symbol	Parameter	Test Condition	Value	Unit
P <sub>D</sub>	Average Power Dissipation	V <sub>CC</sub> = 5 V, V <sub>IO</sub> = 3.3 V (if applicable), T <sub>A</sub> = 25°C, R <sub>L</sub> = 60 Ω, S at 0 V, Input to TXD at 250 kHz, C <sub>L_RXD</sub> = 15 pF. Typical CAN operating conditions at 500 kbps with 25% transmission (dominant) rate.	65	mW
		V <sub>CC</sub> = 5.5 V, V <sub>IO</sub> = 3.6 V (if applicable), T <sub>A</sub> = 125°C, R <sub>L</sub> = 50 Ω, S at 0 V, Input to TXD at 0.5 MHz, C <sub>L_RXD</sub> = 15 pF. Typical high load CAN operating conditions at 1 Mbps with 50% transmission (dominant) rate and loaded network.	135	mW

**Electrical Characteristics**

All test conditions:  $V_{CC} = 4.5\text{ V to }5.5\text{ V}$ ,  $V_{IO} = 3.0\text{ V to }5.5\text{ V}$ ,  $T_A = -40^\circ\text{C to }125^\circ\text{C}$ , unless otherwise noted.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
<b>Power Supply</b>						
$I_{CC}$	Normal Mode (Dominant)	TXD = 0 V, $R_L = 60\ \Omega$ , $C_L = \text{open}$ , $R_{CM} = \text{open}$ , $S = 0\text{ V}$		50	70	mA
		TXD = 0 V, $R_L = 50\ \Omega$ , $C_L = \text{open}$ , $R_{CM} = \text{open}$ , $S = 0\text{ V}$		52	80	mA
	Normal Mode (Dominant-Bus Fault)	TXD = 0 V, $S = 0\text{ V}$ , CANH = -12 V, $R_L = \text{open}$ , $C_L = \text{open}$ , $R_{CM} = \text{open}$		74	150	mA
	Normal Mode (Recessive)	TXD = $V_{CC}$ , $R_L = 50\ \Omega$ , $C_L = \text{open}$ , $R_{CM} = \text{open}$ , $S = 0\text{ V}$		1.3	2.5	mA
	Silent Mode	TXD = $V_{CC}$ , $R_L = 50\ \Omega$ , $C_L = \text{open}$ , $R_{CM} = \text{open}$ , $S = V_{CC}$		1.3	2.5	mA
$I_{IO}$	Normal and Silent Modes	RXD Floating, TXD = $S = 0$ or $V_{IO}$		73	300	$\mu\text{A}$
$UV_{VCC}$	Rising Undervoltage Detection on $V_{CC}$ for Protected Mode			4.0	4.4	V
	Falling Undervoltage Detection on $V_{CC}$ for Protected Mode		3.6	3.9	4.15	V
$V_{HYS (UVVCC)}$	Hysteresis Voltage on $UV_{VCC}$			200		mV
$UV_{VIO}$	Undervoltage Detection on $V_{IO}$ for Protected Mode		1.3		2.75	V
$V_{HYS (UVVIO)}$	Hysteresis Voltage on $UV_{VIO}$ for Protected Mode			150		mV
<b>Pin-S (Mode Select Input)</b>						
$V_{IH}$	High-Level Input Voltage		$0.7 \times V_{IO}$			V
$V_{IL}$	Low-Level Input Voltage				$0.3 \times V_{IO}$	V
$I_{IH}$	High-Level Input Leakage Current	$S = V_{CC}$ or $V_{IO} = 5.5\text{ V}$			30	V
$I_{IL}$	Low-Level Input Leakage Current	$S = 0\text{ V}$ , $V_{CC} = V_{IO} = 5.5\text{ V}$	-2	0	2	$\mu\text{A}$
$I_{kg (OFF)}$	Unpowered Leakage Current	$S = 5.5\text{ V}$ , $V_{CC} = V_{IO} = 0\text{ V}$	-1	0	1	$\mu\text{A}$
<b>Pin- TXD (CAN Transmit Data Input)</b>						
$V_{IH}$	High-Level Input Voltage		$0.7 \times V_{IO}$			V
$V_{IL}$	Low-Level Input Voltage				$0.3 \times V_{IO}$	V
$I_{IH}$	High-Level Input Leakage Current	$S = V_{CC}$ or $V_{IO} = 5.5\text{ V}$	-2.5	0	1	$\mu\text{A}$

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
$I_{IL}$	Low-Level Input Leakage Current	$S = 0\text{ V}, V_{CC} = V_{IO} = 5.5\text{ V}$	-100	-63	-7	$\mu\text{A}$	
$I_{lkg(OFF)}$	Unpowered Leakage Current	$TXD = 5.5\text{ V}, V_{CC} = V_{IO} = 0\text{ V}$	-1	0	1	$\mu\text{A}$	
$C_i$	Input Capacitance <sup>(1)</sup>			4.5		$\mu\text{F}$	
<b>Pin- RXD (CAN Receive Data Output)</b>							
$V_{OH}$	High-Level Output Voltage	Devices with the "V" suffix (I/O level shifting), $I_O = -2\text{ mA}$	$0.8 \times V_{IO}$			V	
$V_{OL}$	Low-Level Output Voltage	Devices with the "V" suffix (I/O level shifting), $I_O = +2\text{ mA}$			$0.2 \times V_{IO}$	V	
$I_{lkg(OFF)}$	Unpowered Leakage Current	$RXD = 5.5\text{ V}, V_{CC} = 0\text{ V}, V_{IO} = 0\text{ V}$	-1	0	1	$\mu\text{A}$	
<b>Driver Electrical Characteristics</b>							
$V_{O(DOM)}$	Bus Output Voltage (Dominant)	CANH	$TXD = 0\text{ V}, S = 0\text{ V},$ $50\ \Omega \leq R_L \leq 65\ \Omega,$ $C_L = \text{open}, R_{CM} = \text{open}$	2.75		4.5	V
		CANL		0.5		2.25	V
$V_{O(REC)}$	Bus Output Voltage (Recessive)	CANH CANL	$TXD = V_{CC}, V_{IO} = V_{CC},$ $S = V_{CC}$ or $0\text{ V}$ <sup>(2)</sup> , $R_L = \text{open}$ (no load), $R_{CM} = \text{open}$	2	$0.5 \times V_{CC}$	3	V
$V_{OD(DOM)}$	Differential Output Voltage (Dominant)	CANH CANL	$TXD = 0\text{ V}, S = 0\text{ V}, 45\ \Omega \leq R_L < 50\ \Omega,$ $C_L = \text{open}, R_{CM} = \text{open}$	1.4		3	V
			$TXD = 0\text{ V}, S = 0\text{ V}, 50\ \Omega \leq R_L \leq 65\ \Omega,$ $C_L = \text{open}, R_{CM} = \text{open}$	1.5		3	V
			$TXD = 0\text{ V}, S = 0\text{ V}, R_L = 2240\ \Omega, C_L = \text{open},$ $R_{CM} = \text{open}$	1.5		5	V
$V_{OD(REC)}$	$V_{OD(REC)}$	$V_{OD(REC)}$	$TXD = V_{CC}, S = 0\text{ V}, R_L = 60\ \Omega, C_L = \text{open},$ $R_{CM} = \text{open}$	-120		12	mV
			$TXD = V_{CC}, S = 0\text{ V}, R_L = \text{open}$ (no load), $C_L = \text{open}, R_{CM} = \text{open}$	-50		50	mV
$V_{SYM}$	Transient Symmetry (Dominant or Recessive) ( $V_{O(CANH)} + V_{O(CANL)} / V_{CC}$ ) <sup>(2)</sup>		$S$ at $0\text{ V}, R_{term} = 60\ \Omega,$ $C_{split} = 4.7\text{ nF}, C_L = \text{open},$ $R_{CM} = \text{open}, T_{XD} = 250\text{ kHz}, 1\text{ MHz}$		1.0		V/V
$V_{SYM\_DC}$	DC Output Symmetry (Dominant or Recessive) ( $V_{CC} - V_{O(CANH)} - V_{O(CANL)}$ ) <sup>(2)</sup>		$S = 0\text{ V}, R_L = 60\ \Omega, C_L = \text{open}, R_{CM} = \text{open}$	-1	0.2	1	V
$I_{OS}$ ( $SS\_DOM$ )	Short-Circuit Steady-State Output Current, Dominant		$S$ at $0\text{ V}, V_{CANH} = -5\text{ V to } 40\text{ V},$ CANH = open, $TXD = 0\text{ V}$	-100			mA
			$S$ at $0\text{ V}, V_{CANL} = -5\text{ V to } 40\text{ V},$ CANH = open, $TXD = 0\text{ V}$			100	mA

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I <sub>OS</sub> (SS_REC)	Short-Circuit Steady-State Output Current, Recessive	-27 V ≤ V <sub>BUS</sub> ≤ 32 V, Where V <sub>BUS</sub> = CANH = CANL, TXD = V <sub>CC</sub> , all modes	-5		5	mA
<b>Receiver Electrical Characteristics</b>						
V <sub>CM</sub>	Common Mode Range, Normal Mode	S = 0 or V <sub>CC</sub> or V <sub>IO</sub>	-30		+30	V
V <sub>IT+</sub>	Positive-Going Input Threshold Voltage, All Modes	S = 0 or V <sub>CC</sub> or V <sub>IO</sub> , -20 V ≤ V <sub>CM</sub> ≤ +20 V			900	mV
V <sub>IT-</sub>	Negative-Going Input Threshold Voltage, All Modes		400			mV
V <sub>IT+</sub>	Positive-Going Input Threshold Voltage, All Modes	S = 0 or V <sub>CC</sub> or V <sub>IO</sub> , -30 V ≤ V <sub>CM</sub> ≤ +30 V			1000	mV
V <sub>IT-</sub>	Negative-Going Input Threshold Voltage, All Modes		400			mV
V <sub>HYS</sub>	Hysteresis Voltage (V <sub>IT+</sub> - V <sub>IT-</sub> ) <sup>(2)</sup>	S = 0 or V <sub>CC</sub> or V <sub>IO</sub>		115		mV
I <sub>lkg(IOFF)</sub>	Power-off (Unpowered) Bus Input Leakage Current	CANH = CANL = 5 V, V <sub>CC</sub> = V <sub>IO</sub> = 0 V			4.8	μA
C <sub>I</sub>	Input Capacitance to Ground (CANH or CANL) <sup>(1)</sup>			35		pF
C <sub>ID</sub>	Differential Input Capacitance <sup>(1)</sup>			20		pF
R <sub>ID</sub>	Differential Input Resistance	TXD = V <sub>CC</sub> = V <sub>IO</sub> = 5 V, S = 0 V, -30	30		80	kΩ
R <sub>IN</sub>	Input Resistance (CANH or CANL)	V ≤ V <sub>CM</sub> ≤ +30 V	15		40	kΩ
R <sub>IN(M)</sub>	Input Resistance Matching: [1 - R <sub>IN(CANH)</sub> / R <sub>IN(CANL)</sub> ] × 100%	V <sub>CANH</sub> = V <sub>CANL</sub> = 5 V	-2%		+2%	

(1) The typ data is based on the bench test by LRC meter E4980AL.

(2) The test data is based on the bench test and design simulation.

## AC Timing Requirements

All test conditions:  $V_{CC} = 4.5\text{ V to }5.5\text{ V}$ ,  $V_{IO} = 3.0\text{ V to }5.5\text{ V}$ ,  $T_A = -40^\circ\text{C to }125^\circ\text{C}$ , unless otherwise noted.

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
<b>Device Switching Characteristics</b>						
$t_{PROP}$ (LOOP1)	Total Loop Delay, Driver Input (TXD) to Receiver Output (RXD), Recessive to Dominant	$S = 0\text{ V}$ , $R_L = 60\ \Omega$ , $C_L = 100\text{ pF}$ , $C_{L(RXD)} = 15\text{ pF}$		100	160	ns
$t_{PROP}$ (LOOP2)	Total Loop Delay, Driver Input (TXD) to Receiver Output (RXD), Dominant to Recessive			110	175	ns
$t_{MODE}$	Mode Change Time, from Normal to Silent or from Silent to Normal			0.15	10	$\mu\text{s}$
<b>Driver Switching Characteristics</b>						
$t_{pHR}$	Propagation Delay Time, High TXD to Driver Recessive (Dominant to Recessive) <sup>(1)</sup>	$S = 0\text{ V}$ , $R_L = 60\ \Omega$ , $C_L = 100\text{ pF}$ , $R_{CM} = \text{open}$		70		ns
$t_{pLD}$	Propagation Delay Time, Low TXD to Driver Dominant (Recessive to Dominant) <sup>(1)</sup>			42		ns
$t_{sk(p)}$	Pulse Skew ( $ t_{pHR} - t_{pLD} $ ) <sup>(1)</sup>			20		ns
$t_R$	Differential Output Signal Rise Time <sup>(1)</sup>			45		ns
$t_F$	Differential Output Signal Fall Time <sup>(1)</sup>			45		ns
$t_{TXD\_DTO}$	Dominant Timeout	$S = 0\text{ V}$ , $R_L = 60\ \Omega$ , $C_L = \text{open}$	1.2		3.8	ms
<b>Receiver Switching Characteristics</b>						
$t_{pRH}$	Propagation Delay Time, Bus Recessive Input to High Output (Dominant to Recessive) <sup>(1)</sup>	$S = 0\text{ V}$ , $C_{L(RXD)} = 15\text{ pF}$		76		ns
$t_{pDL}$	Propagation Delay Time, Bus Dominant Input to Low Output (Recessive to Dominant) <sup>(1)</sup>			59		ns
$t_R$	RXD Output Signal Rise Time <sup>(1)</sup>			10		ns
$t_F$	RXD Output Signal Fall Time <sup>(1)</sup>			10		ns
<b>FD Timing Parameters</b>						
$t_{BIT(BUS)}$	Bit Time on CAN Bus Output Pins with $t_{BIT(TXD)} = 500\text{ ns}$ , All Devices	$S = 0\text{ V}$ , $R_L = 60\ \Omega$ , $C_L = 100\text{ pF}$ , $C_{L(RXD)} = 15\text{ pF}$ ,	435		530	ns

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
	Bit Time on CAN Bus Output Pins with $t_{BIT(TXD)} = 200$ ns, G Device Variants only	$\Delta t_{REC} = t_{BIT(RXD)} - t_{BIT(BUS)}$	155		210	ns
$t_{BIT(RXD)}$	Bit Time on RXD Output Pins with $t_{BIT(TXD)} = 500$ ns, All Devices		400		550	ns
	Bit Time on RXD Output Pins with $t_{BIT(TXD)} = 200$ ns, G Device Variants only		120		220	ns
$\Delta t_{REC}$	Receiver Timing Symmetry with $t_{BIT(TXD)} = 500$ ns, All Devices		-65		40	ns
	Receiver Timing Symmetry with $t_{BIT(TXD)} = 200$ ns, G Device Variants only		-45		15	ns

(1) The test data based on the bench test and design simulation.

## Detailed Description

### Overview

The TPT1051V is a CAN transceiver that meets the ISO11898 high-speed CAN (controller area network) physical layer standard. The device is designed to be used in CAN FD networks up to 5 Mbps with enhanced timing margin and higher data rates in long and highly loaded networks. As designed, the device features cross-wire, overvoltage, loss of ground protection from -42 V to +42 V, overtemperature shutdown, and a -30-V to +30-V common-mode range. The TPT1051V has a secondary power supply input for the I/O level shifting the input pin thresholds and the RXD output level, and the device comes with silent mode which is also commonly referred to as listen-only mode, and it includes many protection features to enhance the device and network robustness.

### Functional Block Diagram

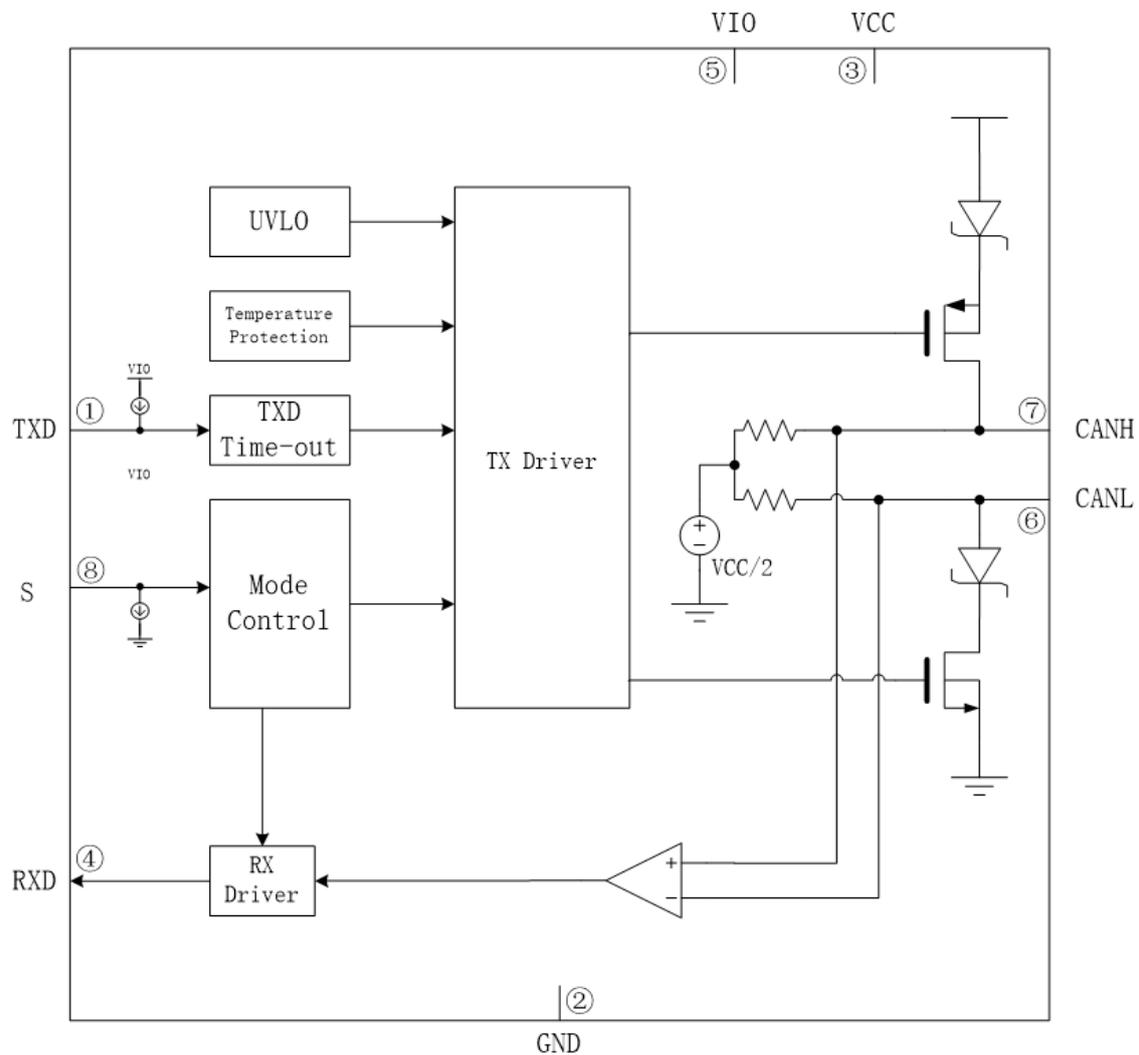


Figure 1. Functional Block Diagram

## Feature Description

### Driver Function Mode

Device	Inputs		Outputs		Driven BUS State
	S	TXD	CANH	CANL	
All Devices	L or open	L	H	L	Dominant
		H or Open	Z	Z	Recessive
	H	X	Z	Z	Recessive

### Receiver Function Table

Device Mode	CAN Differential Inputs $V_{ID} = V_{CANH} - V_{CANL}$	BUS State	RXD Terminal
Normal or Silent	$V_{ID} \geq V_{IT+(MAX)}$	Dominant	L
	$V_{IT-(MIN)} < V_{ID} < V_{IT+(MAX)}$	Indeterminate	Indeterminate
	$V_{ID} \leq V_{IT-(MIN)}$	Recessive	H
	Open ( $V_{ID} \approx 0$ V)	Open	H

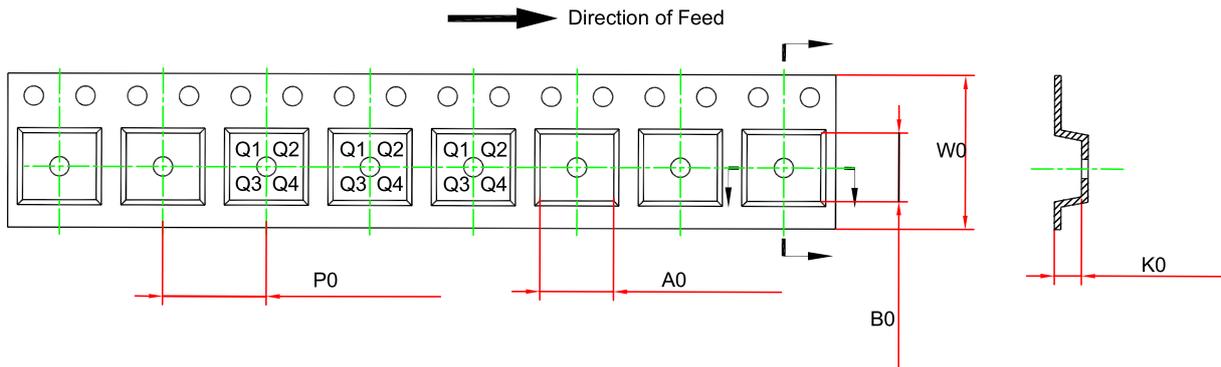
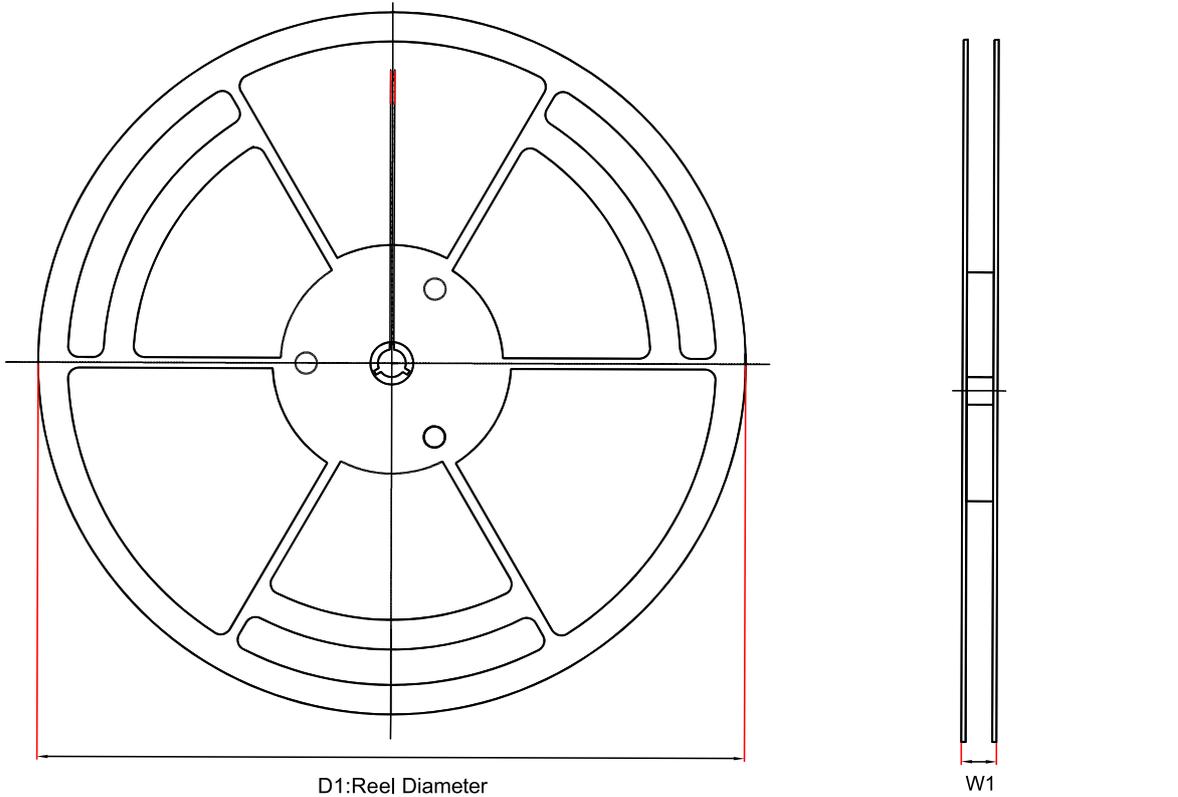
### Normal Mode

A Low level on the pin S selects the normal mode. In normal mode, the transceiver transmits and receives data via the bus lines CANH and CANL. The differential receiver converts the analog data on the bus lines into digital data which is output to the pin RXD. The slopes of the output signals on the bus lines are controlled internally and optimized to guarantee the lowest possible Electro Magnetic Emission (EME).

### Silent Mode

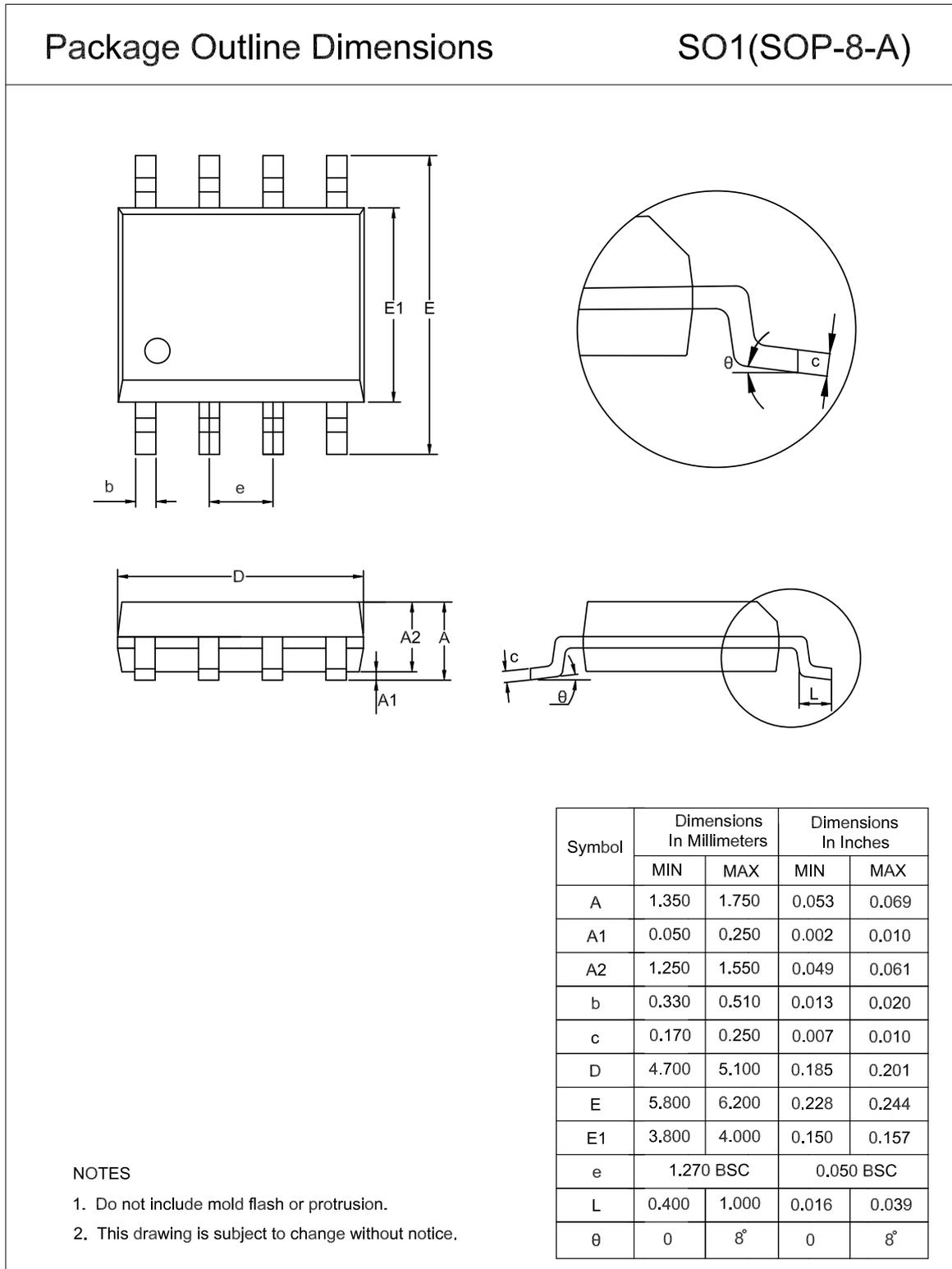
A High level on the pin S selects the silent mode. In silent mode, the transmitter is disabled, releasing the bus pins to a recessive state. All other IC functions, including the receiver, continue to operate as in the normal mode, just like the listen-only mode. The silent mode can be used to prevent a faulty CAN controller from disrupting all network communications.

### Tape and Reel Information

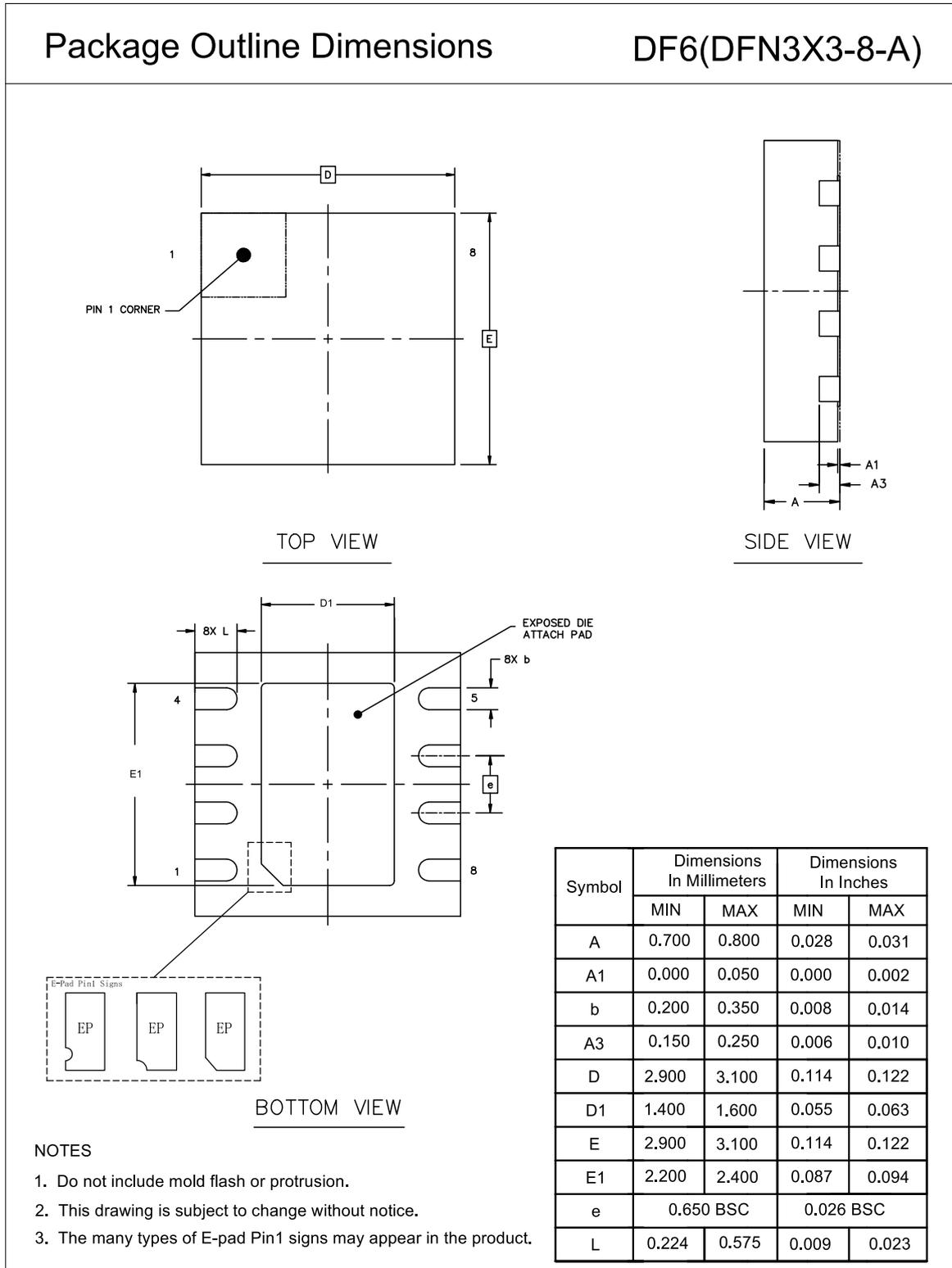


Order Number	Package	D1 (mm)	W1 (mm)	A0 (mm) <sup>(1)</sup>	B0 (mm) <sup>(1)</sup>	K0 (mm) <sup>(1)</sup>	P0 (mm)	W0 (mm)	Pin1 Quadrant
TPT1051V-SO1R	SOP8	330.0	17.6	6.4	5.4	2.1	8.0	12.0	Q1
TPT1051V-DF6R	DFN3×3-8	330.0	17.6	3.3	3.3	1.1	8.0	12.0	Q1

(1) The value is for reference only. Contact the 3PEAK factory for more information.

**Package Outline Dimensions**
**SOP8**


DFN3×3-8



## Order Information

Order Number	Operating Temperature Range	Package	Marking Information	MSL	Transport Media, Quantity	Eco Plan
TPT1051V-SO1R	-40 to 125°C	SOP8	T1051V	3	Tape and Reel, 4000	Green
TPT1051V-DF6R	-40 to 125°C	DFN3x3-8	1051V	3	Tape and Reel, 4000	Green

**Green:** 3PEAK defines "Green" to mean RoHS compatible and free of halogen substances.

## IMPORTANT NOTICE AND DISCLAIMER

**Copyright**© 3PEAK 2012-2025. All rights reserved.

**Trademarks.** Any of the 思瑞浦 or 3PEAK trade names, trademarks, graphic marks, and domain names contained in this document /material are the property of 3PEAK. You may NOT reproduce, modify, publish, transmit or distribute any Trademark without the prior written consent of 3PEAK.

**Performance Information.** Performance tests or performance range contained in this document/material are either results of design simulation or actual tests conducted under designated testing environment. Any variation in testing environment or simulation environment, including but not limited to testing method, testing process or testing temperature, may affect actual performance of the product.

**Disclaimer.** 3PEAK provides technical and reliability data (including data sheets), design resources (including reference designs), application or other design recommendations, networking tools, security information and other resources "As Is". 3PEAK makes no warranty as to the absence of defects, and makes no warranties of any kind, express or implied, including without limitation, implied warranties as to merchantability, fitness for a particular purpose or non-infringement of any third-party's intellectual property rights. Unless otherwise specified in writing, products supplied by 3PEAK are not designed to be used in any life-threatening scenarios, including critical medical applications, automotive safety-critical systems, aviation, aerospace, or any situations where failure could result in bodily harm, loss of life, or significant property damage. 3PEAK disclaims all liability for any such unauthorized use.