

### **Features**

- AEC-Q100 Grade 1 Qualified for Automotive Applications
- Wide Input Voltage Range: 3 V to 36 V
- 1-A Continuous Output Current Capability
- 6-µA Ultra-Low Operating Quiescent Current
- 1-V ±1% Reference Voltage Accuracy
- 35-ns Ultra-Low Minimum on Time
- 2.1-MHz Fixed Switching Frequency
- Integrated 90-mΩ High-Side and 60-mΩ Low-Side Power MOSFETs
- Optional Frequency Spread Spectrum to Reduce EMI
- · Low Drop-out Mode Operation
- · Precision Enable and Input Voltage UVLO
- Cycle-by-Cycle Current Limit and Hiccup When Overload or Short Circuit
- Available in the QFN2X3-12 Package

### **Applications**

- · Automotive Infotainment and Cluster
- · Advanced Driver Assistance Systems
- Body Electronics

### **Description**

The TPP36107Q is a high-efficiency synchronous stepdown regulator with integrated high-side and low-side MOSFETs. It provides up to 1-A output current with peak current mode control for fast loop response.

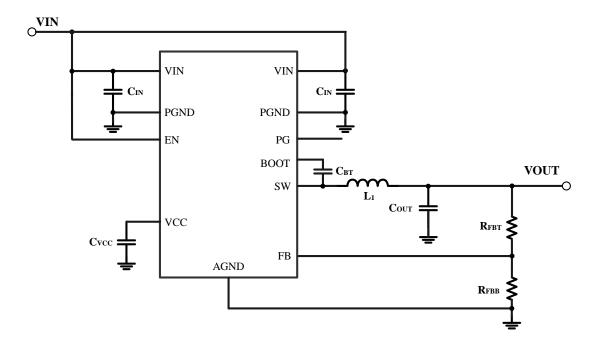
The TPP36107Q operates over a wide input voltage range from 3 V to 36 V with only 6- $\mu$ A ultra-low quiescent current. It is ideal for automotive environments and battery-powered systems due to its extremely low quiescent current.

The TPP36107Q features 35-ns ultra-low minimum on time and low drop-out mode, which can maintain stable operation for high-frequency automotive conditions. EMI performance is specially optimized in the TPP36107Q. The device features a frequency spread spectrum method, optimized symmetrical pinout, and EMI-friendly package to optimize the EMI emissions.

The TPP36107Q has built-in robust protections such as thermal shutdown, UVLO, enable (EN) control, and power good (PG) indicator. Additionally, during the overload or short circuit condition, the cycle-by-cycle current limit and hiccup protections are provided. Thermal shutdown provides reliable and fault-tolerant operation.

The TPP36107Q is available in the QFN2x3-12 package.

## **Typical Application Circuit**





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# **Product Family Table**

Order Number	Switching Frequency		
TPP361072Q-FC6R-S	2.1 MHz		

## **Revision History**

Date	Revision	Notes
2025-07-01	Rev A.0	Initial released.

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## **Pin Configuration and Functions**

TPP36107Q QFN2X3-12 Top View

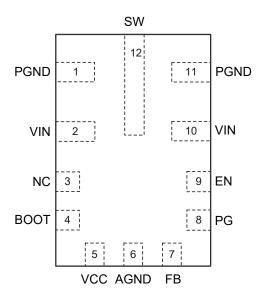


Table 1. Pin Functions: TPP36107Q

Pin No.	Name	I/O	Description
1, 11	PGND	G	Power ground pin. The reference ground of the internal power stage.
2, 10	VIN	Р	Input voltage supply pin. Input capacitors should be placed as close to this pin and the PGND pin as possible.
3	NC	-	Not connected inside the regulator.
4	воот	0	High-side MOSFET gate supply pin. Recommend to connect a 0.1-μF ceramic capacitor between BOOT and SW pins.
5	VCC	0	Internal LDO output pin. The power supply for the driver and control circuits.  Connect a ceramic bypass capacitor from this pin to AGND.
6	AGND	G	Analog ground pin. The reference ground of the internal control circuits. Connect to the power ground plane at the point of the ground of the VCC capacitor.
7	FB	I	Voltage feedback pin. Connect to the middle point of the feedback resistor divider to set the output value.
8	PG	0	Power good indicator pin with open-drain output. Connect a pull-up resistor to the system voltage rail.
9	EN	I_	Enable input pin. The input signal to turn the regulator on or off, High = on, Low = off.
12	SW	0	Switching output pin. Connect this pin to the external inductor.

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### **Specifications**

### Absolute Maximum Ratings (1)

	Parameter	Min	Max	Unit
	VIN	-0.3	42	
1	EN <sup>(2)</sup>	-0.3	VIN + 0.3	
Input	FB	-0.3	5.5	V
	PG	-0.3	22	
	BOOT to SW	-0.3	5.5	
	SW	-0.3	VIN + 0.3	
Output	SW (less than 100 ns)	-3.5	VIN + 0.3	V
	VCC	-0.3	5.5	
	AGND to PGND	-0.3	0.3	
TJ	Junction Temperature	-40	150	°C
Ts	Storage Temperature	-55	150	C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

### **ESD, Electrostatic Discharge Protection**

Symbol	Parameter	Condition	Minimum Level	Unit
НВМ	Human Body Model ESD	AEC-Q100-002 <sup>(1)</sup>	±2000	V
CDM	Charged Device Model ESD	AEC-Q100-011	±750	V

<sup>(1)</sup> AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

### **Recommended Operating Conditions**

	Parameter	Min	Max	Unit
	VIN	3	36	
Buck Regulator	VOUT	1	0.95*VIN	V
	FB	0	5	
Control	EN	0	VIN	V
	PG	0	18	V
TA	Ambient Temperature	-40	125	°C

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<sup>(2)</sup> The voltage on this pin must not exceed the voltage on the VIN pin by more than 0.3 V.



### **Thermal Information**

Package Type	Package Type θ <sub>JA</sub>		<b>Ө</b> лс	Unit	
QFN2X3-12	75.4	20.1	49.5	°C/W	

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### **Electrical Characteristics**

Unless otherwise noted, the min and max limits apply over the recommended operating ambient temperature range ( $T_A$ ) of -40°C to 125°C. Typical values are measured under  $T_A$  = 25°C and represent the most likely parameters normally for reference. The default test conditions:  $V_{IN}$  = 12 V.

Symbol	Parameter	Condition	Min	Тур	Max	Unit
Power Su	ıpply					•
V <sub>IN_MIN</sub>	Minimum Input Voltage	T <sub>A</sub> = 25 °C			3	V
.,		Rising Threshold		2.85	3.2	V
$V_{IN\_UV}$	Under Voltage Lockout Thresholds	Hysteresis		200		mV
I <sub>SD</sub>	Shutdown Supply Current	V <sub>EN</sub> = 0 V, T <sub>A</sub> = 25 °C		0.9	3	μA
IQ	Non-Switching Quiescent Current	V <sub>FB</sub> = 1.2 V		3	15	μA
Enable						
V <sub>EN_H</sub>	Enable High Threshold	Rising Threshold	1.18	1.23	1.31	V
V <sub>EN_HYS</sub>	Enable Hysteresis Threshold	Hysteresis		200		mV
V <sub>EN_LKG</sub>	Enable Pin Leakage Current	V <sub>EN</sub> = 3.3 V		0.2		nA
Soft Star	t			'		·
Tss	Internal Soft-Start Time			4		ms
Voltage F	Reference			<b>'</b>	<b>'</b>	
$V_{FB}$	Feedback Voltage		0.99	1	1.01	V
MOSFETS	S					
R <sub>DSON_H</sub>	High Side on Resistance			90		mΩ
R <sub>DSON_L</sub>	Low Side on Resistance			60		mΩ
Current L	imits					
I <sub>LIMIT_H</sub>	High Side Current Limit (1)	Duty Cycle approaches 0 %	2	3	4	Α
I <sub>LIMIT_L</sub>	Low Side Current Limit			2.5		Α
I <sub>PK_MIN</sub>	Minimum Peak Inductor Current			0.9		Α
I <sub>ZC</sub>	Zero Current Detector Threshold			0.1		Α
Power Go	ood		,			
V <sub>PG_HR</sub>	Power Good High Threshold	Rising Threshold, % of V <sub>FB</sub>	104	107	111	%
V <sub>PG_HF</sub>	Power Good High Threshold	Falling Threshold, % of V <sub>FB</sub>	103	105	109	%
V <sub>PG_LR</sub>	Power Good Low Threshold	Rising Threshold, % of V <sub>FB</sub>	92	94	98	%
V <sub>PG_LF</sub>	Power Good Low Threshold	Falling Threshold, % of V <sub>FB</sub>	90	92	96	%
_	DO D # 4 D	V <sub>IN</sub> = 12 V, V <sub>EN</sub> = 4 V		90	250	
$R_{PG}$	PG Pull-down Resistance	V <sub>EN</sub> = 0 V		80	200	Ω
t <sub>PG</sub>	PG Glitch Filter Delay				170	μs
V <sub>MIN-PG</sub>	Minimum Input Voltage for PG Function	V <sub>EN</sub> = 0 V, 50 μA			2	V
V <sub>PG</sub>	PG Logic Low Output	V <sub>IN</sub> = 1.4 V, V <sub>EN</sub> = 0 V, 50 μA			0.2	V

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Symbol	Parameter	Condition	Min	Тур	Max	Unit
BOOT Su	pply					
VCC	Internal LDO Output Voltage			3.5		V
V <sub>BOOT_UV</sub>	Bootstrap Voltage Undervoltage Threshold			2.2		V
Hiccup M	lode					<u>'</u>
V <sub>HC</sub>	FB Voltage to Trip Hiccup Mode			0.5		V
tнc	Interval Time between Hiccup Burst			35		ms
Switching	g Frequency Timing					
f <sub>SW</sub>	Switching Frequency	400 kHz Version	365	400	465	kHz
fsw	Switching Frequency	1.4 MHz Version	1.2	1.4	1.6	MHz
f <sub>SW</sub>	Switching Frequency	2.1 MHz Version	1.8	2.1	2.4	MHz
f <sub>SS</sub>	Spread Spectrum Span			8		%
Ton_max	Maximum On Time			8		μs
T <sub>ON_MIN</sub>	Minimum On Time			35		ns
T <sub>OFF_MIN</sub>	Minimum Off Time			100		ns
Thermal						
T <sub>SD</sub>	Thermal Shutdown			165		°C
T <sub>SD_HYS</sub>	Thermal Shutdown Hysteresis			15		°C

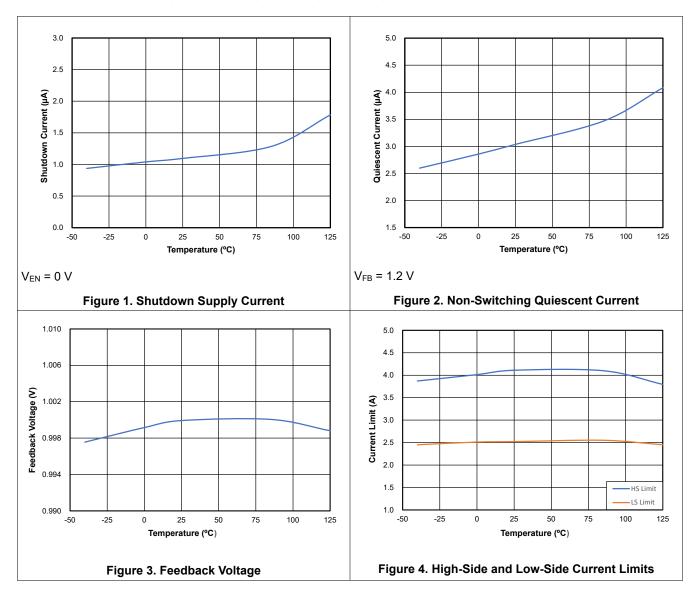
<sup>(1)</sup> High-side MOSFET current limit is affected by the duty cycle. The high-side current limit is higher at a small duty cycle.

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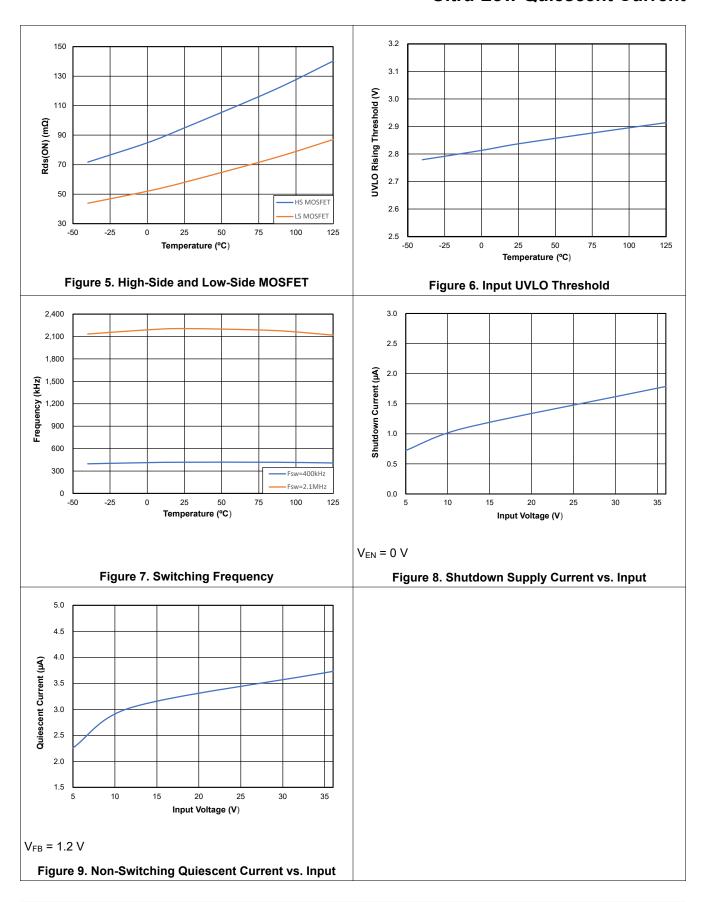
### **Typical Performance Characteristics**

All test conditions:  $V_{IN}$  = 12 V,  $F_{SW}$  = 2.1 MHz,  $V_{OUT}$  = 5 V,  $T_A$  = 25 °C, unless otherwise noted.



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### **Detailed Description**

#### Overview

The TPP36107Q is a high-efficiency synchronous step-down regulator with integrated high-side and low-side MOSFETs. The TPP36107Q can provide up to 1-A output current with high efficiency from light load to full load operating range. The TPP36107Q features a wide input voltage from 3 V to 36 V, selective switching frequencies 400 kHz, 1.4 MHz, and 2.1 MHz for different version parts.

The internal soft-start limits inrush current during power-on. The TPP36107Q also integrates a compensation circuit inside the chip to simplify the loop design. The TPP36107Q features ultra-low operating quiescent current, which makes it suitable for battery-powered applications.

The TPP36107Q is specially optimized to reduce EMI emissions. The device features a frequency spread spectrum method, optimized symmetrical pinout, and EMI-friendly package to optimize the EMI performance. The TPP36107Q integrates full protections such as thermal shutdown, UVLO, enable (EN) control, and power good (PG) indicator. Additionally, during the overload or short circuit condition, the cycle-by-cycle peak and valley current limit and hiccup protections are provided.

### **Functional Block Diagram**

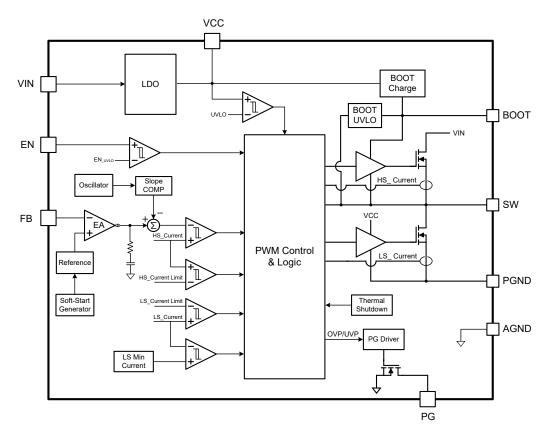


Figure 10. Functional Block Diagram

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### **Feature Description**

#### **Fixed Frequency Peak Current Mode Control**

The TPP36107Q adopts fixed frequency peak current mode control. The feedback voltage is sensed from the resistor divider through the FB pin to compare with the internal voltage reference by an error amplifier. By adjusting the value of the peak current with different output voltage deviations, this voltage control loop is designed to obtain accurate DC voltage regulation. The output of the error amplifier is compared with the sensed peak current by the PWM comparator and controls the on time of the high-side MOSFET. The device also integrates the compensation of the voltage feedback loop to save external components and ensure the stability of the control loop in various working conditions.

An internal oscillator controls the switching frequency and initiates the turn-on of the integrated high-side MOSFET in each duty cycle. During this high-side on period, the SW voltage rises to approximately the input voltage, and the inductor current increases linearly. Once the sensed current through the high-side MOSFET reaches the threshold level set by the COMP voltage of the error amplifier, the PWM comparator turns off the high-side MOSFET. The low-side MOSFET is turned on after a short dead time, and the inductor current is discharged linearly by the low-side MOSFET. The device also utilizes an internal ramp compensation control to avoid sub-harmonic oscillations when the duty cycle is larger than 50%. The COMP voltage is also clamped for current limit conditions and light load operation.

#### **Light Load Operation**

The TPP36107Q utilizes advanced Pulse Frequency Modulation (PFM) control to improve efficiency in light load working conditions. When the load current decreases, the device approaches discontinuous conduction mode first, and the COMP voltage decreases accordingly. The low-side MOSFET is turned off when the zero current detection is triggered to improve system efficiency. When the COMP voltage drops to the low clamped threshold voltage, the device skips a pulse and decreases the switching frequency by extending the non-switching period. During this period, the output voltage decreases due to the load current and capacitor discharge. The high-side MOSFET resumes to turn on once the COMP voltage is higher than the threshold. The device tries to obtain switching pulses with a minimum peak inductor current to reduce the output ripple, and the COMP voltage drops to the clamped value again and triggers another non-switching period.

During the non-switching period, most internal circuits shut down, except for some protection blocks, to reduce power consumption. The TPP36107Q features a typical 6-µA ultra-low quiescent current and can also ensure relatively high efficiency in ultra-low light load conditions and release smooth transitions between CCM, DCM, and PSM modes.

#### Soft Start with Pre-Biased Capability

The TPP36107Q implements a soft start circuit to prevent the inrush current during start-up. The soft start time is fixed internally. When the start-up period begins, the internal reference voltage slowly ramps up.

The TPP36107Q also supports a monotonic start-up with pre-biased loads. If the output voltage is pre-biased to a certain value during start-up, the device disables switching for both high-side and low-side MOSFETs until the soft start reference voltage exceeds the feedback voltage.

#### Frequency Spread Spectrum

The TPP36107Q provides a spread spectrum method that reduces the EMI of the power supply over a wide frequency range. The spread spectrum modulates the switching frequency of the regulator periodically with a relatively low-frequency range to spread the EMI emissions across a wider range. In order to minimize output voltage ripple caused by the spread spectrum, the duty cycle is modified on a cycle-by-cycle basis to maintain a nearly constant duty cycle when dithering is enabled. The spread spectrum function is disabled when the device is in light load, drops out, and triggers minimum on-time conditions.

#### **Low Drop-out Mode**

As the duty cycle increases, where the input voltage approaches the output voltage level, the required off time of the high-side MOSFET approaches its minimum off time. When the minimum off time is reached, the TPP36107Q automatically

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extends the high side on time and reduces the switching frequency. The device can realize 98% max duty cycle in drop-out condition. In this condition, the dropout voltage difference between input and output is influenced by the on-resistance of the high-side MOSFET, the DCR of the power inductor, and the maximum duty cycle achieved. For different load currents, the 5-V output drop-out voltage is shown below.

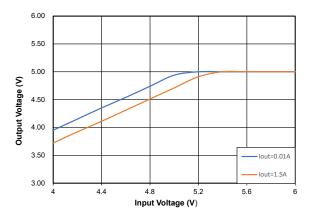


Figure 11. Low Drop-out Voltage

#### **Minimum on Time**

As the duty cycle is decreasing, where the conversion ratio is very low, the required on time of the high-side MOSFET approaches its minimum on time. The TPP36107Q features a typical 35-ns ultra-low minimum on time and can support smaller duty cycles for high-frequency power systems. Also, the device can automatically reduce the switching frequency when the minimum on time is reached.

#### **Power Good**

The device employs an open-drain output PG signal to check whether the output voltage is operating within the normal range. The external pull-up voltage resource is recommended to be less than 5.5 V (such as VCC) with a 1-kΩ resistor. Once the feedback voltage is within 94% and 107% of the internal reference voltage, the PG is pulled up by the external resistor. Once the feedback voltage is lower than 92% or higher than 105% of the internal reference voltage, the PG is pulled low.

#### **Protection**

#### **Undervoltage Lockout (UVLO)**

Typically, the device features 2.85-V input undervoltage lockout rising threshold. The UVLO threshold integrates a 200-mV hysteresis to make a desired hysteresis for input voltage. It can be adjusted by using an EN pin with an external resistor divider.

V<sub>UVLO R</sub> is the desired system-level undervoltage protection rising threshold voltage, and V<sub>UVLO F</sub> is the desired system-level undervoltage protection falling threshold voltage. VEN R and VEN F are the rising and falling enable thresholds. RuvLO H and R<sub>UVLO</sub> L can be calculated below.

$$V_{UVLO_R} = \left(1 + \frac{R_{UVLO_H}}{R_{UVLO_L}}\right) * V_{EN_R}$$

$$V_{UVLO_F} = \left(1 + \frac{R_{UVLO_H}}{R_{UVLO_L}}\right) * V_{EN_F}$$
(2)

$$V_{UVLO\_F} = \left(1 + \frac{R_{UVLO\_H}}{R_{UVLO\_L}}\right)^* V_{EN\_F}$$
 (2)

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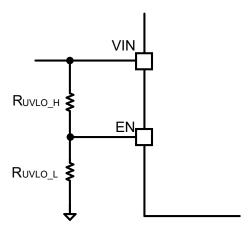


Figure 12. UVLO Adjustment

#### **Current Limits**

The TPP36107Q employs both cycle-by-cycle peak and valley current limits to protect the high-side and low-side power switch from overload. Once the inductor current reaches the high-side peak current limit, the high-side MOSFET is turned off immediately to avoid the inductor current from further increasing. When the low-side valley current limit is triggered, the next duty cycle is held until the inductor current recovers within the valley current limit. Both peak and valley current limits determine the maximum output current of the device, and the valley current limit can prevent inductor current from running away during unexpected overload or short circuit conditions. Also, the device integrates a zero-current detector to turn off the low-side MOSFET at light loads. Delay needs to be taken into account, which may cause the sensed current to be slightly different from open-loop current limits.

#### **Short Circuit Protection**

To further ensure the converter's protection during prolonged overload or short circuits, the device features hiccup overload protection. When the inductor peak current is clamped at the peak current limit, the output voltage falls out of normal regulation. Furthermore, if the feedback-sensed voltage drops below one threshold, the device enters the hiccup mode. Entering this mode, the device stops switching and restarts a normal soft-start operation after the recovery time. If the overload condition still exists, the device keeps switching with the peak current limit and turns off the switches again. The device can automatically recover to normal operation when the overload condition is removed. The hiccup function is disabled at the normal soft start period to avoid being mistakenly triggered.

#### **Thermal Shutdown**

Once the junction temperature rises above the internal over-temperature shutdown threshold, the internal temperature sensor shuts down the device. The device recovers operating when the junction temperature falls below the threshold with hysteresis.

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## **Application and Implementation**

#### Note

Information in the following application sections is not part of the 3PEAK's component specification and 3PEAK does not warrant its accuracy or completeness. 3PEAK's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### **Application Information**

The TPP36107Q is typically used to convert a wide range of input voltages to the desired output voltage, which can be set by the feedback resistor divider. Because of the ultra-low minimum on time and high efficiency, the TPP36107Q is very suitable for 2.1-MHz high-frequency applications to increase system power density. The device is integrated with the internal compensation and can operate over a wide range of external components and working conditions. However, some typical parameters and external component values are recommended to help speed up the developing process. In most power systems, a lower voltage rail such as 5 V/3.3 V is typically used for microcontrollers, I/Os, and other low-voltage components. The following application lists the typical schematic and application information for a 5-V output buck regulator system.

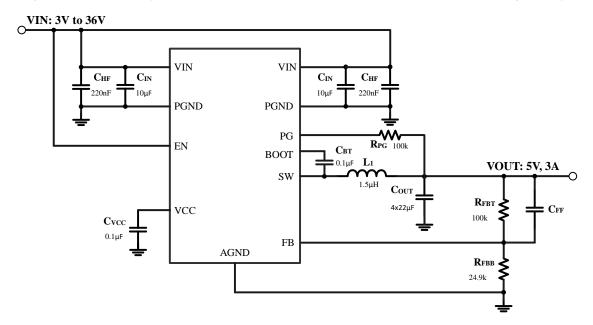


Figure 13. Typical Application Circuit

#### **Setting Output Voltage**

The external resistor divider network connected to the FB pin sets the output voltage. The resistance of the divider is a compromise between noise suppression and output current consumption. The smaller value resistor reduces noise sensitivity but also increases the quiescent current of the system and reduces light load efficiency. It is typically recommended to select a 100 k $\Omega$  resistor for the top feedback resistor. If low quiescent current and high light load efficiency are required, a 1-M $\Omega$  top feedback resistor can be selected, and one feedback capacitor can be used to improve the phase margin. Once the top feedback resistor is selected, the value of the bottom feedback resistor can be calculated with the equation below.

$$R_{FBB} = \frac{V_{FB} * R_{FBT}}{V_{OUT} - V_{FB}}$$
 (3)

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where  $V_{FB}$  is the internal reference voltage, which is typically 1 V for TPP36107Q. For a 5 V output, if  $R_{FBT}$  = 100 k $\Omega$ ,  $R_{FBB}$  = 24.9 k $\Omega$  is chosen. If  $R_{FBT}$  = 1 M $\Omega$ ,  $R_{FBB}$  = 249 k $\Omega$  is chosen.

#### **Inductor Selection**

The selection of the inductor affects steady-state operation as well as transient behavior and loop stability. These factors make it the most important component in power regulator design. There are three important inductor specifications: inductor value, DC resistance, and saturation current. The inductor value is designed based on the desired peak-to-peak ripple current and is typically chosen to be in the range of 20% to 40% of the maximum output current. Once the desired inductor ripple current is selected, the inductor value can be calculated with the equation below.

$$L = \frac{V_{OUT}}{f_{SW} * \Delta I_L} * \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \tag{4}$$

where  $f_{SW}$  is the switching frequency and  $\Delta I_L$  is the inductor ripple current.

When the inductor current approaches its saturation level, the effective inductance can fall to a fraction of the zero current value. Although one high-side valley current limit is integrated to avoid the current runaway, the inductor current can rise to a high value very rapidly if the inductor is saturated. The inductor saturation current must leave a safe margin from the high-side peak current limit in the worst-case conditions. The inductor's RMS current and peak current can be calculated with the equation below.

$$I_{L\_PEAK} = I_{OUT} + \frac{\Delta I_L}{2}$$
 (5)

$$I_{L\_RMS} = \sqrt{I_{OUT}^2 + \frac{\Delta I_L}{12}}$$
 (6)

### **Input Capacitor Selection**

The input capacitor of the step-down regulator is used to supply the AC input current and maintain a stable DC input voltage. At least a 10-µF capacitance of a ceramic input capacitor is recommended. Additional input capacitance may be required to meet ripple and transient requirements. High-quality ceramic capacitor, X5R, or X7R, is recommended because of the low equivalent series resistance (ESR) characteristics and small capacitance variations over a temperature range. In addition, one small value and small case size, ceramic capacitor (such as 100 nF, 0603 package) is recommended to be used at the input and be placed as close as possible to the VIN and GND pins. This can provide a high-frequency bypass for the internal control circuits. The input capacitor can be calculated with the equation below when the input voltage ripple is determined.

$$\Delta V_{IN} = \frac{I_{OUT}}{f_{SW} * C_{IN}} * \frac{V_{OUT}}{V_{IN}} * \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$
 (7)

where C<sub>IN</sub> is the input capacitance value.

The input capacitor ripple current rating should be greater than the maximum input current ripple. The RMS current of the input capacitor can be calculated with the equation below.

$$I_{CIN\_RMS} = I_{OUT} * \sqrt{\frac{V_{OUT}}{V_{IN}} * \left(1 - \frac{V_{OUT}}{V_{IN}}\right)}$$
(8)

The worst case for the input voltage ripple and RMS current occurs when the duty cycle is 50%.

### **Output Capacitor Selection**

The output capacitance is mainly selected to meet the requirements of the output ripple and voltage change during a load transient. Then the control loop is compensated for the output capacitor selected. The output voltage ripple is related to the capacitance and ESR of the output capacitor. Assuming the capacitor with small ESR, the minimum output capacitance needed for a given output ripple voltage can be calculated with the equation below.

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$$C_{OUT} > \frac{\Delta I_L}{8 * f_{SW} * \Delta V_{OUT}}$$
(9)

where  $\Delta I_L$  is the inductor ripple current and  $\Delta V_{OUT}$  is the output voltage ripple.

If a large ESR capacitor is used, it contributes additional output ripple. ESR ripples can be neglected for ceramic capacitors, but must be considered if electrolytic capacitors are used. The maximum ESR for a given ripple can be calculated with the equation below.

$$R_{ESR} < \frac{\Delta V_{OUT}}{\Delta I_L} - \frac{1}{8 * f_{SW} * C_{OUT}}$$
 (10)

The effective value of the ceramic capacitor decrease should be considered when the output DC bias voltage is added across the capacitors. The RMS current of the output capacitor can be calculated with the equation below.

$$I_{COUT\_RMS} = \frac{V_{OUT} * (V_{IN\_MAX} - V_{OUT})}{\sqrt{12} * V_{IN\_MAX} * L * f_{SW}}$$
(11)

where V<sub>IN MAX</sub> is the maximum input voltage, and L is the selected inductor value.

#### **Bootstrap Capacitor Selection**

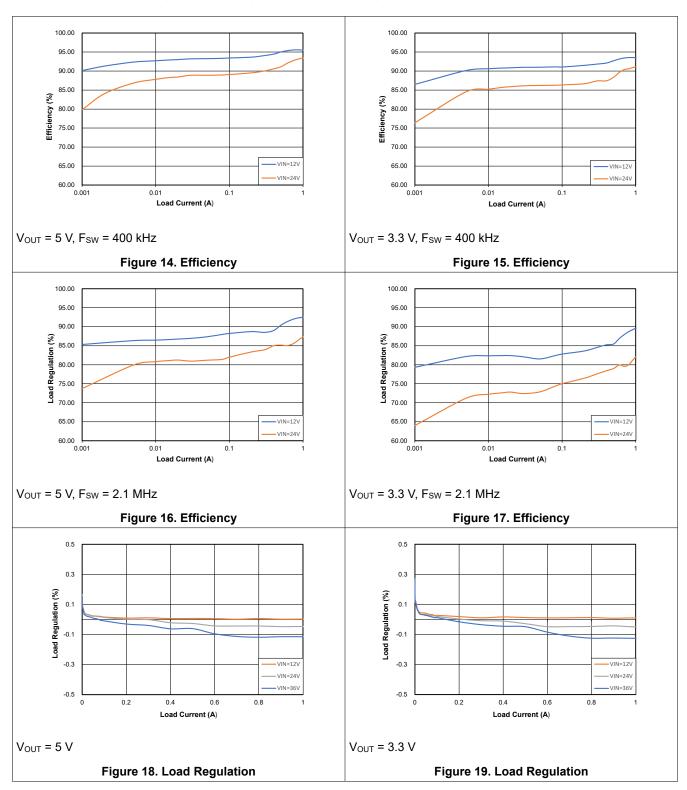
A typical 0.1-µF bootstrap capacitor is connected between the BOOT pin and the SW pin. It is recommended to use a ceramic capacitor with X5R or superior grade dielectric and a voltage rating of 10 V or higher.

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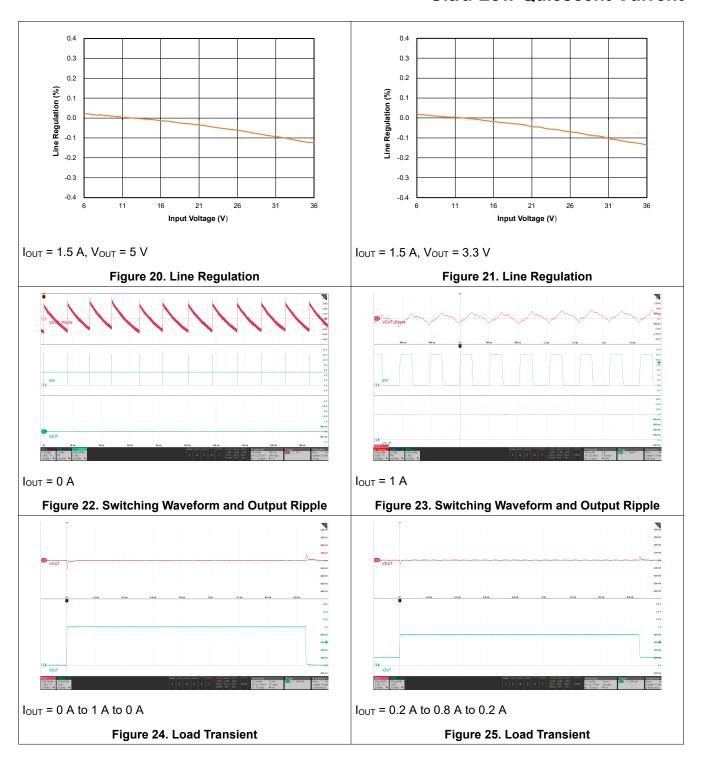


### **Application Waveforms**

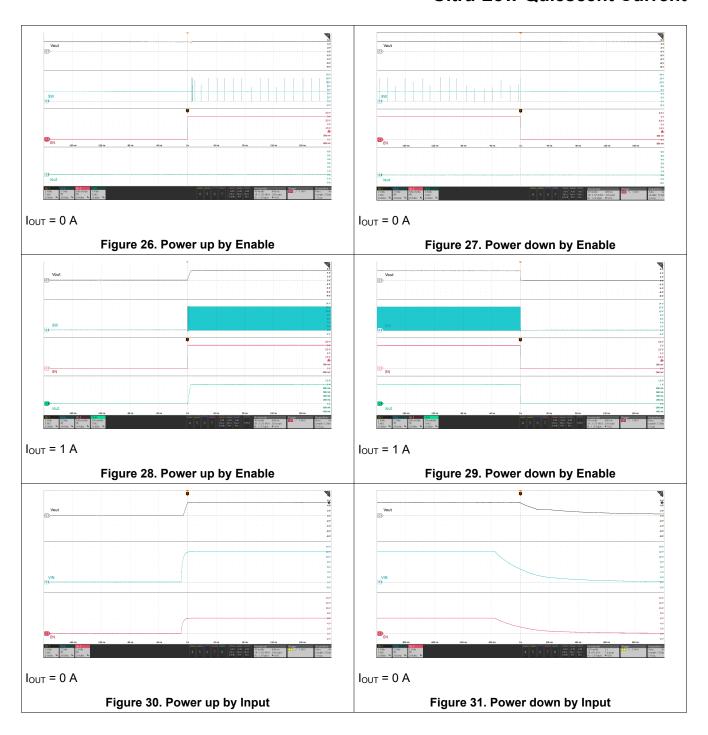
All test conditions:  $V_{IN}$  = 12 V,  $F_{SW}$  = 2.1 MHz,  $V_{OUT}$  = 5 V,  $T_A$  = 25 °C, unless otherwise noted.



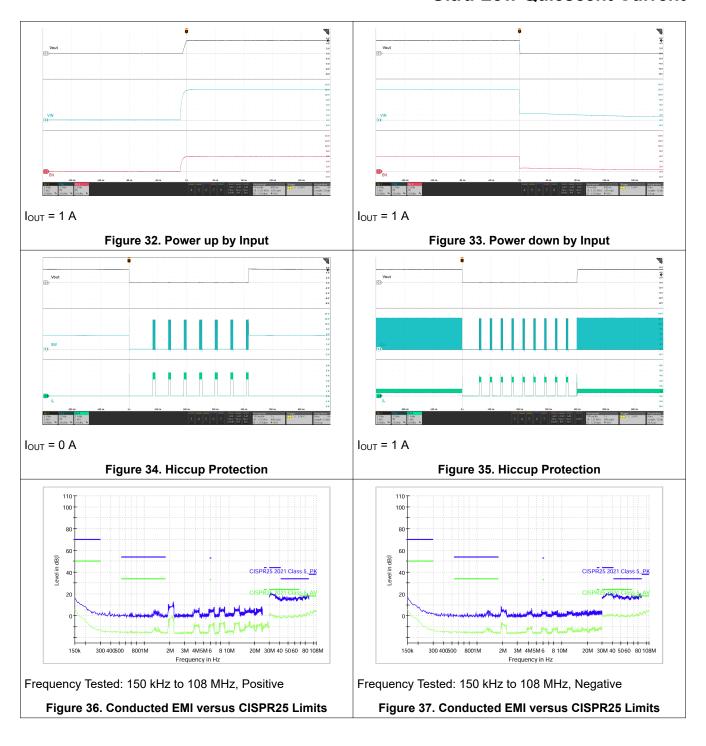




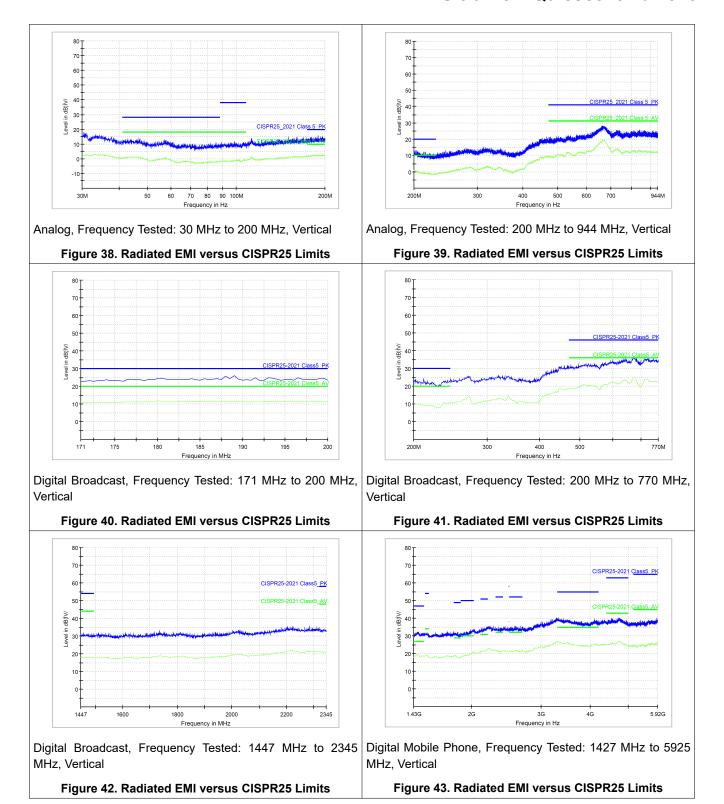












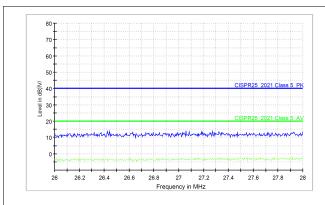
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CISPR25\_2021 Class 5 PK

200M

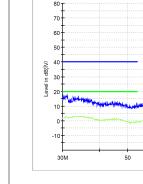


## 3-V to 36-V Input, 1-A Synchronous Step-Down Regulator with 6-μA Ultra-Low Quiescent Current



Mobile, Frequency Tested: 26 MHz to 28 MHz, Vertical

Figure 44. Radiated EMI versus CISPR25 Limits



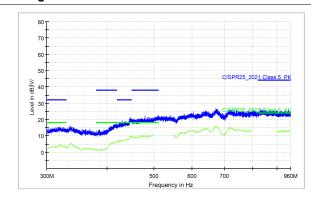
Mobile, Frequency Tested:30 MHz to 200 MHz, Vertical

Figure 45. Radiated EMI versus CISPR25 Limits

70

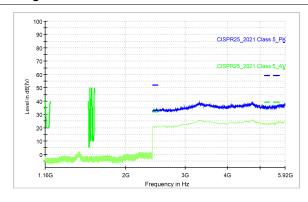
80

90 100M



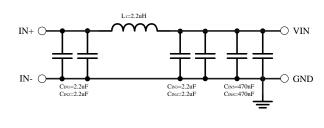
Mobile, Frequency Tested: 300 MHz to 960 MHz, Vertical

Figure 46. Radiated EMI versus CISPR25 Limits



Mobile, Frequency Tested: 1156 MHz to 5925 MHz, Vertical

Figure 47. Radiated EMI versus CISPR25 Limits



 $F_{SW} = 2.1 MHz$ 

Figure 48. Recommended Input EMI Filter



## Layout

### **Layout Guideline**

The performance of switching regulators heavily depends on the quality of the PCB layout, especially for thermal design and EMI design. Even if the schematic design is good, a bad PCB layout can disrupt the operation of the regulator.

- 1. Place a low ESR ceramic capacitor as close to the VIN pin and the ground as possible.
- 2. Make sure the top switching loop with power has the lowest impendence of grounding.
- 3. Use a large ground plane to connect to PGND directly. And add vias near PGND.
- 4. The inductor should be placed close to the SW pin to minimize the SW area.
- 5. The FB terminal is sensitive to noise so the feedback resistor should be located as close as possible to the chip.
- 6. Keep the connection of the input capacitor and the VIN pin as short and wide as possible.

### **Layout Recommendations**

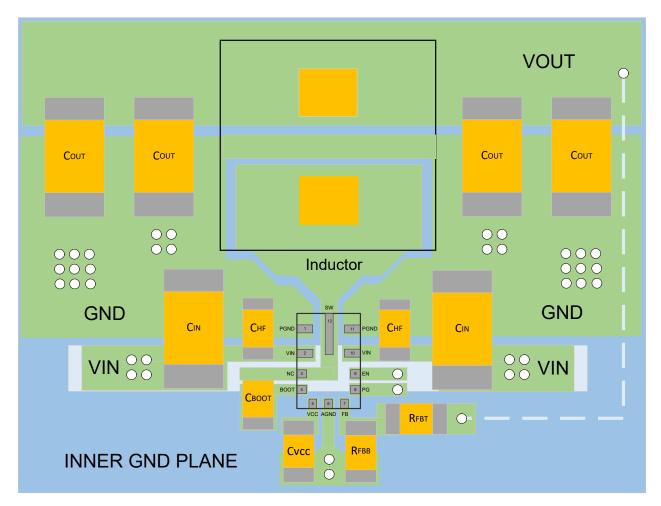


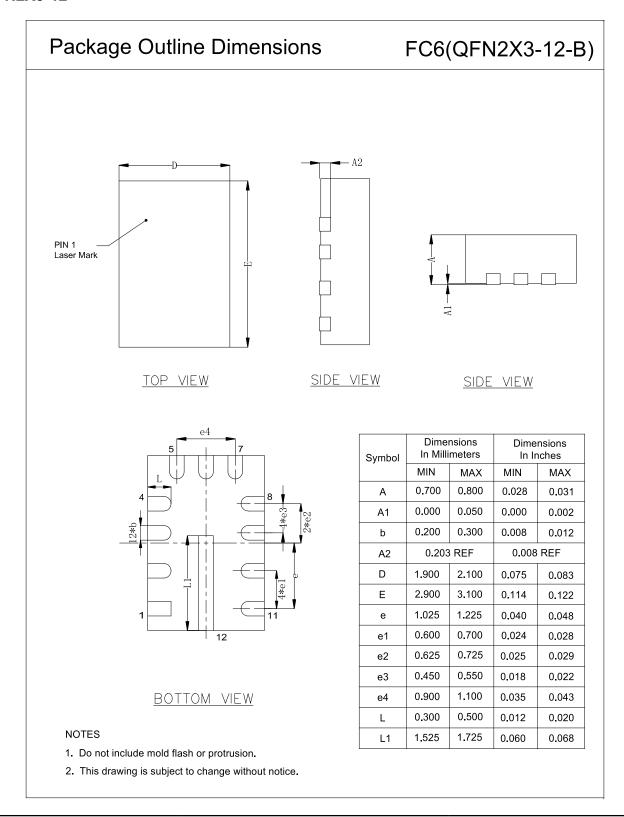
Figure 49. Layout Example

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## **Package Outline Dimensions**

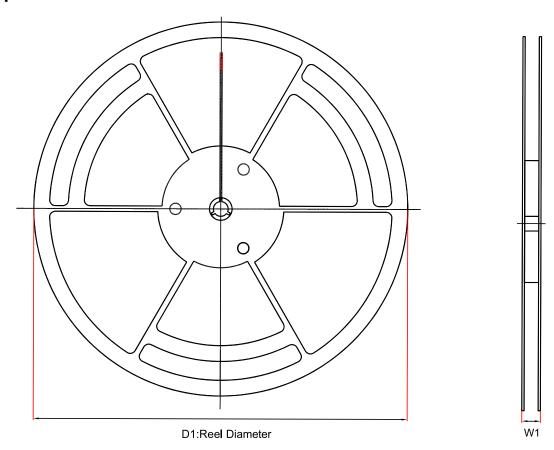
### QFN2X3-12

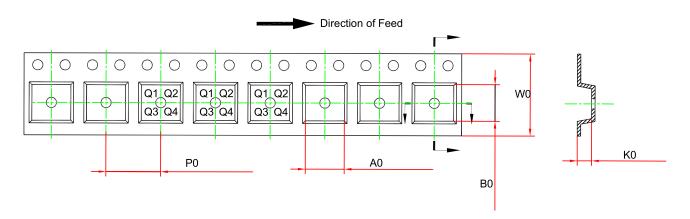


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## **Tape and Reel Information**





Order Number	Package	D1 (mm)	W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P0 (mm)	W0 (mm)	Pin1 Quadrant
TPP361072Q-FC6R-S	QFN2X3-12	178	11.4	2.3	3.2	1.0	4.0	8.0	Q1



### **Order Information**

Order Number	Order Number Operating Temperature Range		Marking Information	MSL	Transport Media, Quantity	Eco Plan
TPP361072Q-FC6R-S	−40 to 125°C	QFN2X3-12	172	MSL2	Tape and Reel, 3000	Green

**Green**: 3PEAK defines "Green" to mean RoHS compatible and free of halogen substances.

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