

### **Features**

- 8-Channel Smart Low-side Driver Array
  - 40-V Max Operating Voltage, 48-V Abs Max Voltage
  - $500\text{-m}\Omega$  Low- $R_{DS(ON)}$  with Maximum 1.5-A Driver Capability
  - Integrated Free-wheeling Diodes for Inductive Loads
  - Parallel Channel Driving Capability
- 10-MHz High-speed 16-bit Shift Register Interface
  - Input Noise Filtering with Daisy-chain Communication
- · Diagnostics and Protection
  - Power On Reset
  - Over-Current Protection
  - Short-Circuit Protection
  - Over-Temperature Protection
  - Open-drain Fault Alarm

## **Applications**

- Relays, Solenoids, Unipolar Stepper Motors
- Electric Expension Valves, Linear Valves
- LEDs and Heaters
- PLC Digital Outputs
- Electromagnetic Loads

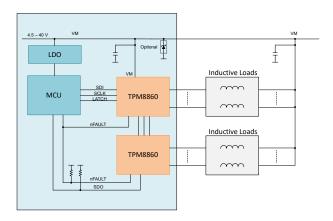
### **Description**

The TPM8860 provides an 8-ch low-side driver with channel independent protection and diagnostics. It has low  $R_{DS(ON)}$  MOSFET array with free-wheeling diodes to support all kinds of loads, resistive, inductive and capacitive. It supports single high-voltage supply

It supports high-speed shift register interface with daisychain individually control each channel. Over-current protection, short-circuit and open-circuit allows controller to protect the system from faulty loads. Open-drain fault output allows controller to respond to fault scneario with interrupt input.

Multiple devices can be connected in daisy-chain configuration to save MCU I/Os. The device also provides undervoltage lockout, over-temperature shutdown protection.

## **Typical Application Circuit**





## **Table of Contents**

Features	1
Applications	1
Description	1
Typical Application Circuit	1
Revision History	3
Pin Configuration and Functions	4
Specifications	5
Absolute Maximum Ratings <sup>(1)</sup>	5
ESD, Electrostatic Discharge Protection	5
Recommended Operating Conditions	6
Thermal Information	6
Electrical Characteristics	7
Typical Performance Characteristics	9
Detailed Description	11
Overview	11
Functional Block Diagram	11
Feature Description	12
Application and Implementation	15
Application Information	15
Typical Application	17
Layout	18
Layout Guideline	18
Layout Example	18
Tape and Reel Information	19
Package Outline Dimensions	20
TSSOP24	20
ETSSOP24	21
Order Information	22
IMPORTANT NOTICE AND DISCLAIMER	23



# **Revision History**

Date	Revision	Notes
2023-07-11	Rev.P0	Initial revision
2023-10-24	Rev.P1	Updated application diagram

www.3peak.com 3 / 23 EA20230701P1



# **Pin Configuration and Functions**

TPM8860-TSBR ETSSOP16 Package Top View

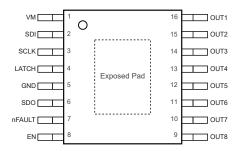


Table 1. Pin Functions: TPP8860-TSBR

Pin	Name	I/O	Description
1	VM	Р	Motor power supply, connect to 10μF capacitor with 0.1μF close to VM pin
2	SDI	I	Serial interface data input
3	SCLK	I	Serial interface clock input
4	LATCH	1	Serial interface latch input
5	GND	G	Device ground
6	SDO	0	Serial interface data output, push-pull output
7	nFAULT	OD	Open-drain fault output
8	EN	I	Output enable. Logic high to enable all outputs, logic low to disable all outputs.
9	OUT8	0	Output channel 8
10	OUT7	0	Output channel 7
11	OUT6	0	Output channel 6
12	OUT5	0	Output channel 5
13	OUT4	0	Output channel 4
14	OUT3	0	Output channel 3
15	OUT2	0	Output channel 2
16	OUT1	0	Output channel 1

www.3peak.com 4 / 23 EA20230701P1



## **Specifications**

### Absolute Maximum Ratings (1)

	Parameter	Min	Max	Max
VM	Power Supply Voltage	-0.3	48	V
VIVI	Power Supply Voltage (100-ns Pulse)	-0.3	50	V
EN, LATCH, SCLK, SDI	Input Voltage	-0.3	7	V
SDO, nFAULT	Output Voltage	-0.3	7	V
	Power Output Voltage	-0.3	48	V
Vouтx	Power Output Voltage (100-ns Pulse)	-0.3	50	V
TJ	Maximum Junction Temperature		150	°C
T <sub>A</sub>	Operating Temperature Range	-40	125	°C
T <sub>STG</sub>	Storage Temperature Range	-65	150	°C
TL	Lead Temperature (Soldering 10 sec)		260	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

### **ESD, Electrostatic Discharge Protection**

Symbol	Parameter	Condition	Minimum Level	Unit
НВМ	Human Body Model ESD	ANSI/ESDA/JEDEC JS-001 (1)	4	kV
CDM	Charged Device Model ESD	ANSI/ESDA/JEDEC JS-002 (2)	1	kV

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

www.3peak.com 5 / 23 EA20230701P1

<sup>(2)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.



## **Recommended Operating Conditions**

	Parameter	Min	Max	Unit
VM	Power Supply Voltage	5	40	V
EN, SDI, SCLK, LATCH	Logic Input Voltage	0	5.5	V
SDO, nFAULT	Open Drain Output Voltage	0	5.5	V
V <sub>OUTx</sub>	Output Voltage	0	40	V
	Continuous Output Current		1.5	А
Іоитх	Peak Output Current		2	Α
I <sub>VM</sub>	Reverse Current		4	Α
I <sub>GND</sub>	Ground Current		4	Α
TJ	Maximum Junction Temperature		150	°C
T <sub>A</sub>	Operating Temperature Range	-40	125	°C

### **Thermal Information**

Package Type	θ <sub>JA</sub>	θυς	Unit
ETSSOP16	62.8	52.6	°C/W

www.3peak.com 6 / 23 EA20230701P1



### **Electrical Characteristics**

All test condition is at  $V_M$  = 12 V,  $T_A$  = -40°C to +125°C, unless otherwise noted.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Power Supp	oly					
I <sub>VM</sub>	VM Operating Supply Current	VM = 24 V		1	4	mA
VuvLO_rising	VM Under-voltage-lock-out Rising Edge	VM rising edge			4.4	V
$V_{\sf UVLO\_falling}$	VM Under-voltage-lock-out Falling Edge	VM falling edge			4.4	V
Logic Input	s / Outputs (EN, LATCH, SDI, SCL	K, nFAULT, SDO)				
VIL	Input Low Voltage Threshold		0.7		1.3	V
V <sub>IH</sub>	Input High Voltage Threshold		1		1.5	V
I <sub>IL</sub>	Input Low Current	V <sub>IN</sub> = 0 V	-20		20	μΑ
I <sub>IH</sub>	Input High Current	V <sub>IN</sub> = 3.3 V			100	μΑ
R <sub>PD</sub>	Input Pull-down Resistance		60	100	130	kΩ
V <sub>OL</sub>	Output Low Voltage	I <sub>O</sub> = 5 mA			0.5	V
OH(nFAULT)	nFAULT Output High Leakage Current	Vo = 3.3 V	-1		1	μA
R <sub>PU</sub>	SDO Pull-up Resistance	Pull up to internal regulator		1.4		kΩ
V <sub>SDO_H</sub>	Output High Voltage	I <sub>O</sub> = 0.1 mA, VM = 5 V - 40 V, steady state	2.5	4.5	5.9	V
Isdo_src	SDO Source Current	VM = 24 V, V <sub>SDO</sub> = V <sub>SDO_H</sub> - 0.5V		10		mA
I <sub>SDO_SINK</sub>	SDO Sink Current	VM = 24 V, V <sub>SDO</sub> = 0.3 V		50	250	mA
Outputs						
Rds(ON)	Output Low-side MOSFET on- resistance	VM = 24 V, Io= 500 mA, T <sub>J</sub> = 25°C		0.5		Ω
R <sub>ds(ON)</sub>	Output Low-side MOSFET on- resistance	VM = 24 V, I <sub>O</sub> = 500 mA, T <sub>J</sub> = 150°C		0.8	1.2	Ω
I <sub>OPEN_OFF</sub>	Open Load Detection Current during off State			30	50	μA
VF	Highside Diode Forward Voltage	VM = 24 V, I <sub>SINK</sub> = 500 mA, T <sub>J</sub> = 25°C		0.9		V
I <sub>HSD_lkg</sub>	Highside Diode Leakage Current	VM = 24 V, T <sub>J</sub> = 25°C	-50		50	μΑ
t <sub>OUT_risetime</sub>	Output Risetime	VM = 24 V, T <sub>J</sub> = 25°C, Resistive load		90		ns
$t_{OUT\_falltime}$	Output Falltime	VM = 24 V, T <sub>J</sub> = 25°C, Resistive load		90		ns
Diagnostics	and Protection					

www.3peak.com 7 / 23 EA20230701P1



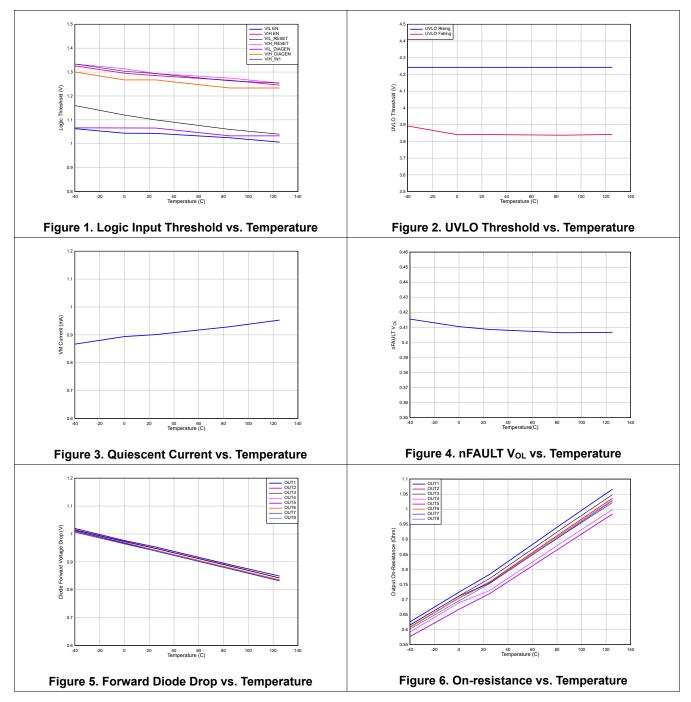
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I <sub>(OCP_TH)</sub>	Over-current Protection Threshold		1.65		2.8	А
t <sub>(OCP_deg)</sub>	Over-current Protection Deglitch Time			3.5		μs
V <sub>(OL_TH)</sub>	Open Load Detection Threshold			1.2		V
t <sub>(OL_deg)</sub>	Open Load Detection Deglitch Time		7		17	μs
I <sub>(OL_off)</sub>	Off-time Open-Load Source Current			30	50	μA
t <sub>RETRY</sub>	Over-current Retry Timer			100		ms
t <sub>TSD</sub>	Thermal Shutdown Threshold		150	175		°C
t <sub>TSD_HYS</sub>	Thermal Shutdown Threshold Hysteresis			15		°C

www.3peak.com 8 / 23 EA20230701P1



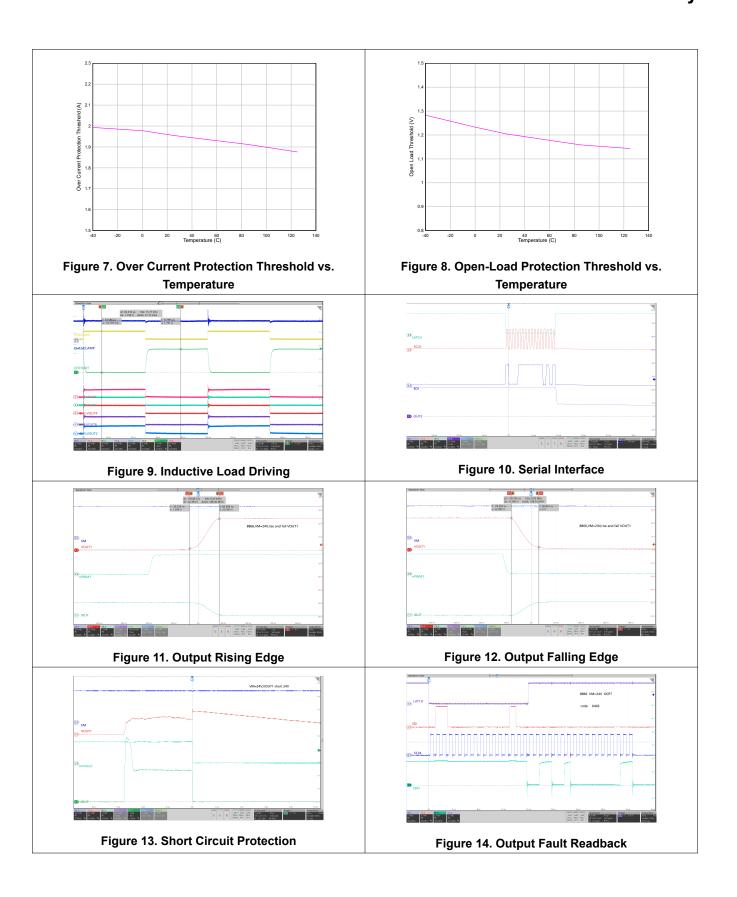
### **Typical Performance Characteristics**

All test condition:  $V_{IN}$  =12 V,  $T_A$  =+ 25°C, unless otherwise noted.



www.3peak.com 9 / 23 EA20230701P1







### **Detailed Description**

#### Overview

The TPM8860 is a smart high-voltage high-current low-side driver array with full diagnostics and protection. The device supports maximum 40-V seperated supply and driver voltage. 8-Ch lowside driver can be controlled individually via serial interface. Each output channel has integrated free-wheeling diode path for inductive loads such as solenoids, motors, electric expansion valves and relays. The device has protection features includes supply undervoltage monitoring, over-current protection, load open-circuit and short-circuit diagnostics, and over-temperature protection. Open-drain fault bus allows hardware interrupt for MCU to handle fault scenarios easily.

The device supports daisychain connection of multiple devices together as well as isolated interface with 3PEAK digital isolators.

### **Functional Block Diagram**

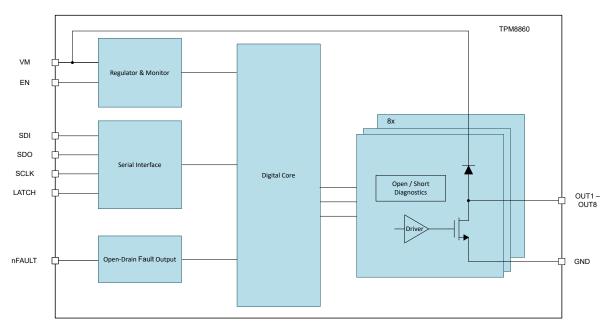


Figure 15. Functional Block Diagram

www.3peak.com 11 / 23 EA20230701P1



#### **Feature Description**

#### Supply and Reference

The TPM8860 supports single voltage rail VM. VM includes an undervoltage lockout (UVLO) monitor to prevent issues at low supply voltages. It is recommended to use 10-µF capacitors on each rail to suppress voltage transients when driving inductive loads. When inductive loads may surge higher than 40-V, 3PEAK recommends to use TVS to supress transient voltage.

The device has a EN input with an internal pull-down. When EN is low, the device is in a reset state, clearing register maps and tri-stating the SDO pin. When RESET is high, the device is in normal operation and can communicate via the serial interface.

#### **Output Enable**

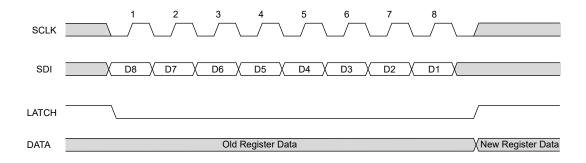
The TPM8860 provides an active high output enable, EN, to control the device outputs. When EN is low, the outputs are disabled with register map cleared; When EN is high, the outputs are enabled. It has an internal pull-down resistor and can be left unconnected or connected to ground for desired functionality.

#### **Serial Communication**

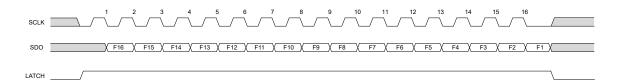
#### **Serial Interface**

The TPM8860 device supports a high-speed shift-register serial interface with daisy-chain capability. The Serial Data Output (SDO) pin is configured as a push-pull output, connected to the internal 3.3-V voltage rail to enable high-speed communication.

During a write operation, when the device selection LATCH is low, on each rising edge of the serial clock (SCLK), the device shifts the Serial Data Input (SDI) into the internal shift register and updates the Serial Data Output (SDO) with the last bit of the shift register.



During a read operation, when LATCH is high, microcontroller sends out the serial clock and shift internal fault indicator registers out. On each falling edge of SCLK, the device shifts out the 16-bit data from the internal register to SDO.



#### **Output Driver**

www.3peak.com 12 / 23 EA20230701P1



The device features an array of 8 low-side drivers, each consisting of a low-side MOSFET and a high-side recirculation diode. Each channel is capable of handling a maximum current of 1.5 A, although the total device current should also consider thermal effects. The drivers can accommodate both inductive and resistive loads.

When a channel is turned on, the low-side MOSFET conducts, allowing current to flow from the external load through the low-side MOSFET to the device ground. When the channel is turned off, the inductive current will continue to flow, but it will be recirculated through the internal diode to the VCLAMP pin.

It is crucial to ensure that the VCLAMP pin can handle the inductive energy. To protect against overvoltage, we recommend using an external clamp diode connected to the VCLAMP pin. The other side of the external clamp diode can be connected to either the VM or GND, depending on the specific application requirements.

#### **Output Control by Serial Interface**

Each channel of the device can be individually enabled or disabled. This can be achieved through the serial interface. When Dx is set to 1, the corresponding channel is turned on, and when it is set to 0, the channel is turned off.

#### **Output Diagnostics**

#### **Open-drain Fault**

The TPM8860 features an open-drain output called nFAULT. This output is used to indicate the occurrence of a fault. When a fault condition occurs, the nFAULT pin is pulled down, signaling the fault status to the external circuitry. The microcontroller can also force the nFAULT pin low by setting the FORCE\_FAULT bit to 1. This allows the microcontroller to actively monitor the fault feedback loop by simulating a fault condition and observing the corresponding response through the nFAULT pin.

#### **Open-Load Diagnostics**

During the off time of each channel, the TPM8860 has the capability to detect open loads. This is done by applying a small current of 30 µA to the OUTx pin and comparing the voltage at OUTx with an internal threshold called Vth\_open. If the output is open (no load connected), the small current will pull down the voltage at OUTx to ground, triggering the open comparator.

It's important to note that an open load condition will not prevent the channel from turning on.

If any of the channels trigger an open load fault, the nFAULT pin will be pulled low, indicating the occurrence of a fault.

#### **Short & Over Current Protection**

Each channel of the device is equipped with a short-circuit protection circuit to limit the output current and shut down the channel if an overcurrent fault is detected. If an output channel is shorted to the supply, the output current will be internally clamped to protect the channel.

During the on-time of the channel, it continuously monitors the output current. If the current exceeds a predefined threshold for a duration longer than the deglitch timer, an overcurrent fault is triggered.

By default, the overcurrent protection is set to latched off.

In the event of an OCP fault on any channel, the nFAULT pin will be pulled low to indicate the fault condition.

By default, the overcurrent protection is latched off, meaning it remains active until manually cleared. To clear the overcurrent fault, user can use commands like CLR FAULT, CLR OCP, or set the MASK OCPx bit.

To enhance system reliability, the TPM8866 offers an autoretry feature. When CONF\_AUTORECOVERY is set to 1, a channel that experiences an overcurrent fault will automatically retry after a 100-ms delay. During the retry time, the overcurrent flags (FLAG\_OCPx and FLAG\_FAULT) remain set. The retry timer is synchronized between channels, eliminating the need for separate timers for each channel.

Each channel has an independent overcurrent protection fault mask bit, MASK\_OCPx. If MASK\_OCPx is set to 1, the channel will mask the overcurrent protection, allowing the channel to remain on even if an overcurrent condition occurs. If the current exceeds the short protection threshold, the current will be clamped at the short protection threshold.

www.3peak.com 13 / 23 EA20230701P1



The extended OCP deglitch timer, enabled by setting CONF\_EXTOCP to 1, is specifically designed to support capacitive loads in situations where an overcurrent protection (OCP) event may occur. Capacitive loads can cause a momentary surge in current when initially connected, which might trigger the OCP fault detection mechanism.

By increasing the deglitch timer from the standard duration of  $3.5 \mu s$  to  $10 \mu s$  in the extended mode, the device allows for a longer duration to evaluate the current waveform before considering it as an overcurrent condition. This extended timer helps prevent false triggering of the OCP fault due to capacitive loads and allows the device to operate effectively with such loads.

In the event of an OCP fault in any of the channels, the FLAG\_OCP and FLAG\_FAULT will be set, and the nFAULT pin will be pulled low to indicate the fault condition.

#### **Thermal Protection**

The TPM8860 device includes thermal protection to prevent damage from excessive temperatures. When the junction temperature surpasses over temperature threshold, the thermal shutdown (FLAG\_TSD) feature is triggered, turning off all output channels. Once the temperature drops below the threshold with hystersis, normal operation resumes. Thermal protection ensures safe operation by monitoring and reacting to high temperatures.

www.3peak.com 14 / 23 EA20230701P1



## **Application and Implementation**

#### Note

Information in the following application sections is not part of the 3PEAK's component specification and 3PEAK does not warrant its accuracy or completeness. 3PEAK's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

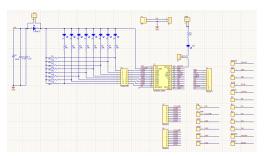
### **Application Information**

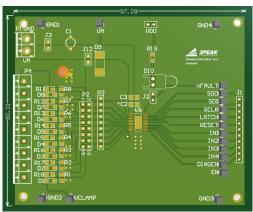
#### **PLC Digital Output**

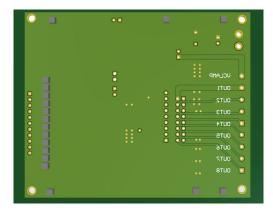
#### **Serial Communication**

The TPM8866 is designed for digital output control in industrial PLC (Programmable Logic Controller) applications. It features SPI communication interface and integration with digital isolators to provide reliable output control.

In industrial PLC applications, digital outputs are commonly used to control various external devices such as motors, valves, lights, etc. The TPM8866 offers an 8-channel low-side driver array, with each channel capable of independent switching control. Through the SPI interface, the main controller can send commands to TPM8866 to control the on/off state of each channel.







Commonly used serial commands are as follows:

- OUT1 open Register: 08, Hex Code: 8012, Binary Code: 1000,0000,0001,0010
   This command opens channel OUT1.
- OUT1-8 open Register: 08, Hex Code: 8FF5, Binary Code: 1000,1111,1111,1001
   This command opens channels OUT1 to OUT8 simultaneously.
- OUT1-8 close Register: 08, Hex Code: 8001, Binary Code: 1000,0000,0000,0001

www.3peak.com 15 / 23 EA20230701P1



This command closes channels OUT1 to OUT8 simultaneously.

- Read DOUT Register: 00, Hex Code: 0000, Binary Code: 0000,0000,0000,0000
   This command reads the status of the DOUT register.
- Read Open fault register Register: 05, Hex Code: 5006, Binary Code: 0101,0000,0000,0110
   This command reads the open fault register to check for any open circuit faults.
- Read OCP fault register Register: 06, Hex Code: 6004, Binary Code: 0110,0000,0000,0100
   This command reads the over-current protection (OCP) fault register to check for any over-current faults.
- Wmask OCP fault Register: 09, Hex Code: 9FFA, Binary Code: 1001,1111,1111,1010
   This command writes a mask to the OCP fault register to enable/disable OCP fault detection for specific channels.
- Rmask OCP fault Register: 01, Hex Code: 100F, Binary Code: 0001,0000,0000,1111
  This command reads the OCP fault mask register to check the OCP fault detection mask for each channel.
- Wmask Open fault Register: 0A, Hex Code: AFF8, Binary Code: 1010,1111,1111,1000
   This command writes a mask to the open fault register to enable/disable open circuit fault detection for specific channels.
- Rmask Open fault Register: 02, Hex Code: 200D, Binary Code: 0010,0000,0000,1101
   This command reads the open fault mask register to check the open circuit fault detection mask for each channel.
- CONF OCP Autoretry Register: 0B, Hex Code: B106, Binary Code: 1011,0001,0000,0110
   This command configures the automatic retry feature for over-current protection (OCP). Setting the bit enables auto retry after 100ms.
- CONF PWMMAP Register: 0B, Hex Code: B209, Binary Code: 1011,0010,0000,1001
   This command configures the PWM mapping selection for the channels. The specific channel-to-PWM mapping is determined by the bits in this register.
- Read CONF Register: 03, Hex Code: 3002, Binary Code: 0011,0000,0000,0010 This command reads the CONF register to check the configuration settings.
- Read fault flag Register: 04, Hex Code: 4009, Binary Code: 0100,0000,0000,1001
   This command reads the fault flag register to check for any fault flags.
- CLR register Register: 0C, Hex Code



Figure 16. Serial Communication Write

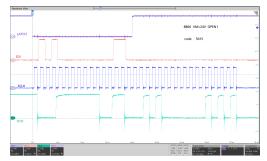


Figure 17. Serial Communication Read

www.3peak.com 16 / 23 EA20230701P1

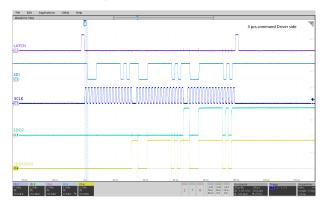


#### Multiple Device in Daisy Chain with Digital Isolator

To ensure reliability and safety, digital isolators are incorporated into the system. These isolators provide signal isolation between the main controller and the TPM8866, protecting the signal transmission from noise, electromagnetic interference, and other detrimental factors. This isolation design enhances system stability and reliability, while safeguarding the main controller from external disturbances.

By combining SPI communication with digital isolators, the TPM8866 delivers a robust solution for digital output control in industrial PLC applications. It enables precise output control and shields the main controller from external interference. Whether in factory automation, machinery control, or other industrial domains, the TPM8866 provides reliable digital output control capabilities for industrial PLCs.

Below shows an example of 3pcs of devices in daisychain communication:



### **Typical Application**

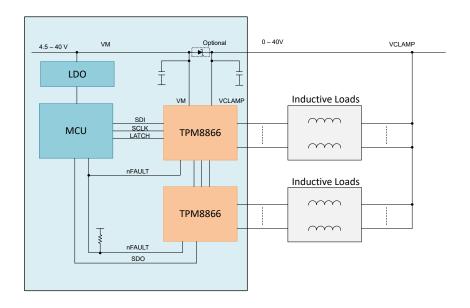


Figure 18. Typical Application Circuit

www.3peak.com 17 / 23 EA20230701P1

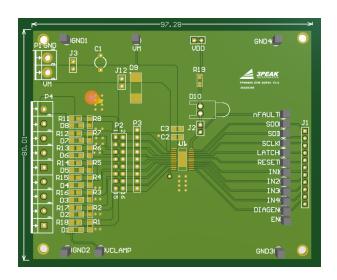


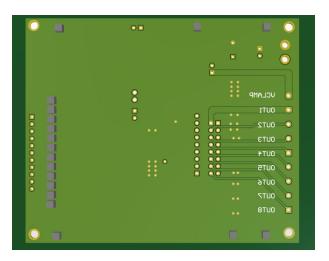
## Layout

### **Layout Guideline**

- Both input capacitors and output capacitors must be placed to the device pins as close as possible.
- It is recommended to bypass the input pin to ground with a 0.1-µF bypass capacitor.
- It is recommended to use wide and thick copper to minimize I×R drop and heat dissipation.
- Exposed pad must be connected to the PCB ground plane directly, the copper area must be as large as possible.

### **Layout Example**

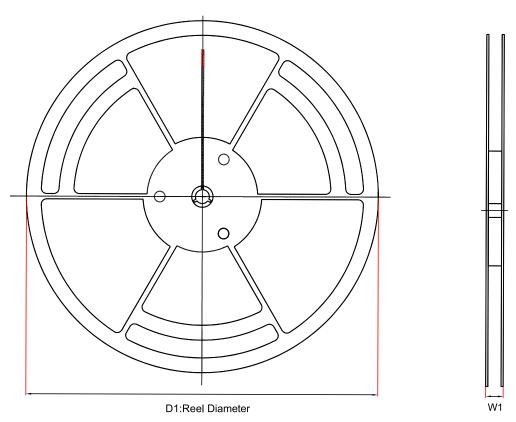


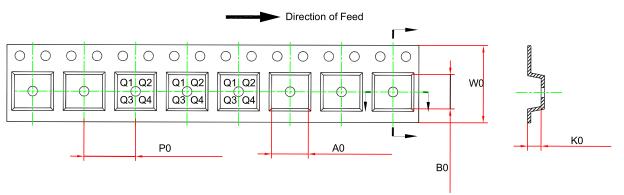


www.3peak.com 18 / 23 EA20230701P1



# **Tape and Reel Information**





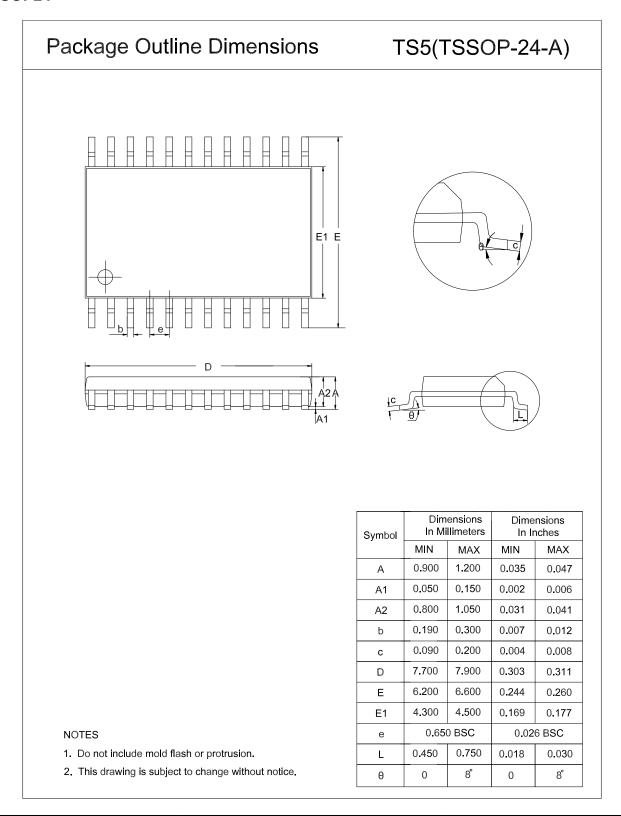
Order Number	Package	D1 (mm)	W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P0 (mm)	W0 (mm)	Pin1 Quadrant
TPM8866- TSDR	ETSSOP2 4	330	17.4	6.9	8.3	1.6	8.0	16.0	Q1
TPM8866- TS5R	TSSOP24	330	17.4	6.8	8.3	1.6	8.0	16.0	Q1

www.3peak.com 19 / 23 EA20230701P1



## **Package Outline Dimensions**

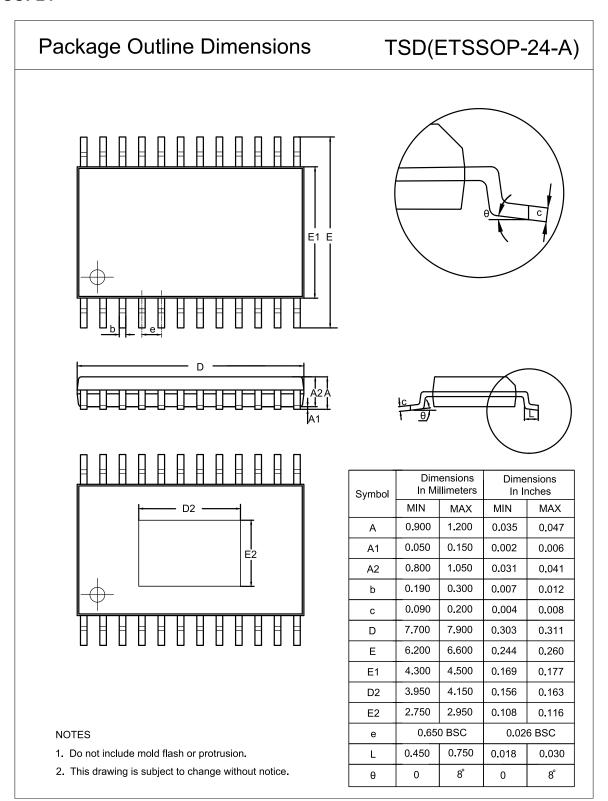
### TSSOP24



www.3peak.com 20 / 23 EA20230701P1



#### ETSSOP24





### **Order Information**

Order Number	Operating Temperature Range	Package	Marking Information	MSL	Transport Media, Quantity	Eco Plan
TPM8866-TSDR	−40 to 125°C	ETSSOP24	M8866	3	Tape and Reel, 4000	Green
TPM8866-TS6R	−40 to 125°C	TSSOP24	M8866	3	Tape and Reel, 4000	Green

<sup>(1)</sup> Future product, contact 3PEAK factory for more information and sample.3PEAK defines "Green" to mean RoHS compatible and free of halogen substances.

Green: 3PEAK defines "Green" to mean RoHS compatible and free of halogen substances.

www.3peak.com 22 / 23 EA20230701P1



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