

Features

Enhanced PWM Rejection

• Wide Common-Mode Voltage

— Operational Voltage: −4 V to 95 V

Survival Voltage: -8 V to 100 V

Supply Voltage: 3.0 V to 5.5 V

Excellent CMRR

150-dB DC CMRR

115-dB AC CMRR at 50 kHz

Accuracy and Zero-Drift Performance

120-µV Voltage Offset (Max, −40°C to 125°C)

0.3% Gain Error (Max, -40°C to 125°C)

• Bandwidth: 1 MHz (For A0, A1, A2, A3, A4 Version)

· Excellent Start-up and Power-off Response

· Gain Options for Voltage Output

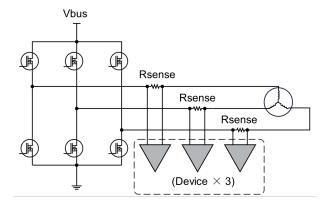
TPA133A0: 10 V/V
TPA133A1: 20 V/V
TPA133A2: 50 V/V
TPA133A3: 100 V/V
TPA133A4: 200 V/V
TPA133A5: 500 V/V

-40°C to 125°C Operation Range

Applications

- Current Sensing (High-Side and Low-Side)
- · Solenoid and Valve Control
- Power Management

Typical Application Circuit

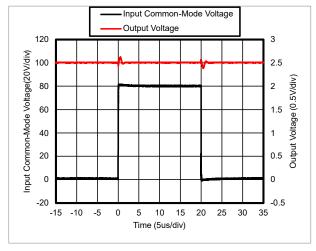


Description

The TPA133 is a current-sense amplifier with a very wide input common-mode voltage range from -4 V to 95 V with a small-signal bandwidth of 1 MHz. The enhanced PWM rejection allows the TPA133 to accommodate the solenoids and motors applications. The device features high-precision accuracy specifications of Vos and the gain error, which makes it ideal for the small signal conditioning interfacing with a high-accuracy ADC.

Fixed gains are optional: 10 V/V, 20 V/V, 50 V/V, 100 V/V, 200 V/V, and 500 V/V. The device offers breakthrough performance throughout the temperature range of -40°C to +125°C. The device is offered SOT23-8 and MSOP8 packages.

Many systems, including motors and solenoids, employ PWM signals for modulation or control purposes. However, these PWM signals generate fast common-mode voltage transitions that oscillate between high voltage and ground potential. This can pose a challenge for the current measurement circuitry, as it may result in undesirable output voltage fluctuations. To address this issue, the device incorporates an advanced PWM rejection feature. This feature minimizes the impact of common-mode voltage transitions and ensures stable and reliable output voltage.



Enhanced PWM Rejection Function



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Revision History

Date	Revision	Notes
2025-02-10	Rev.A.0	Initial version

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Pin Configuration and Functions

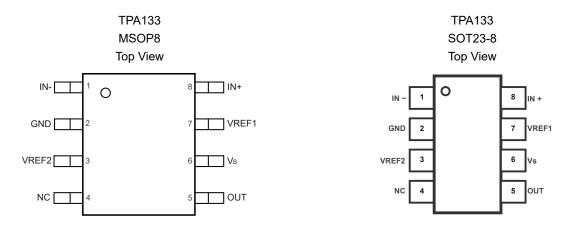


Table 1. Pin Functions: TPA133

Pin	No.	Nama	1/0	Description.			
MSOP8	SOT23-8	Name	I/O	Description			
1	1	IN-	I	Inverting input.			
2	2	GND		Ground.			
3	3	VREF2	ı	Reference 2 voltage, 0 V to V _S .			
4	4	NC		Not connected.			
5	5	OUT	0	Output voltage.			
6	6	Vs		Power supply, 3 V to 5.5 V.			
7	7	VREF1	I	Reference 1 voltage, 0 V to V _S .			
8	8	IN+	I	Noninverting input.			

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Specifications

Absolute Maximum Ratings (1)

	Parameter	Min	Max	Unit
Vs	Supply Voltage		6	٧
	Input Common Voltage	-8	100	V
	Input Differential Voltage, (IN+) − (IN−)	-10	10	V
	REF1, REF2, NC Inputs	GND - 0.3	V _S + 0.3	V
	Output	GND - 0.3	V _S + 0.3	V
	Input Current: +IN, -IN	-10	+10	mA
TJ	Maximum Operating Junction Temperature		150	°C
T _A	Operating Temperature Range	-40	125	°C
T _{STG}	Storage Temperature Range	-65	150	°C
TL	Lead Temperature (Soldering, 10 sec)		260	°C

⁽¹⁾ Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

ESD, Electrostatic Discharge Protection

Symbol	Parameter	Condition	Minimum Level	Unit
НВМ	Human Body Model ESD	ANSI/ESDA/JEDEC JS-001 (1)	2	kV
CDM	Charged Device Model ESD	ANSI/ESDA/JEDEC JS-002 (2)	1.5	kV

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

Thermal Information

Package Type	θ _{JA}	θυς	Unit
MSOP8	210	45	°C/W
SOT23-8	196	70	°C/W

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⁽²⁾ JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



Electrical Characteristics

All test conditions: $V_S = 3 \text{ V}$, $T_A = 25^{\circ}\text{C}$, $V_{SENSE} = (IN+) - (IN-)$, $V_{CM} = (IN+) = 95 \text{ V}$, $V_{REF1} = V_{REF2} = V_S / 2$, unless otherwise noted.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Input						
Vos	Input Offset Voltage	$V_{SENSE} = 0$ mV, $T_A = -40$ °C to 125°C		±20	±120	μV
Vos TC	Input Offset Voltage Drift	$V_{SENSE} = 0$ mV, $T_A = -40$ °C to 125°C		0.15	0.5	μV/°C
V _{CM} ⁽¹⁾	Specified Common-Mode Input Range	V _{SENSE} = 0 mV, T _A = -40°C to 125°C	-4		95	V
VCM (1)	Survival Common-Mode Input Range	V _{SENSE} = 0 mV, T _A = -40°C to 125°C	-8		100	V
CMRR (2)	Common-Mode Rejection Ratio	$-4 \text{ V} < \text{V}_{\text{CM}} < 95 \text{ V}, T_{\text{A}} = -40^{\circ}\text{C} \text{ to}$ 125°C	130	150		dB
IB	Input Bias Current	Vsense = 0 mV		1	50	μA
los	Input Offset Current	V _{SENSE} = 0 mV		0.1	1	μA
Noise RT						
en	Input Voltage Noise Density (2)	f = 1 kHz		80		nV/√Hz
Output						
		TPA133A0		10		V/V
		TPA133A1		20		V/V
<u> </u>	Cain	TPA133A2		50		V/V
G	Gain	TPA133A3		100		V/V
		TPA133A4		200		V/V
		TPA133A5		500		V/V
		TPA133A0, TPA133A1, TPA133A2, TPA133A3, TPA133A4		±0.05	±0.2	%
	Gain Error	$T_A = -40^{\circ}\text{C}$ to 125°C TPA133A0, TPA133A1, TPA133A2, TPA133A3, TPA133A4			±0.3	%
GE		TPA133A5		±0.1	±0.3	%
		T _A = -40°C to 125°C TPA133A5			±0.5	%
	Non-Linearity Error ⁽²⁾	GND + $10\text{mV} \le V_{\text{OUT}} \le V_{\text{S}} - 200 \text{ mV},$ T _A = -40°C to 125°C		±0.01		%
GE TC	Survival Common-Mode Input Range MRR (2) Common-Mode Rejection Ratio Input Bias Current Input Offset Current Input Voltage Noise Density (2) Input Gain Gain Gain Fror ve. Temperature	$T_A = -40^{\circ}\text{C}$ to 125°C TPA133A0, TPA133A1, TPA133A2, TPA133A3		1.5	10	ppm/°C
(~)		T _A = -40°C to 125°C TPA133A4, TPA133A5		1.5	12	ppm/°C

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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
C_{LOAD}	Maxim Capacitive Load	No Oscillation		1		nF
		$V_S = 5.5 \text{ V}, \text{ R}_L = 10 \text{ k}\Omega \text{ to GND}$		8	25	mV
V _{OH}	Output Swing from V _S	V_S = 5.5 V, R_L = 10 k Ω to GND, T_A = -40° C to 125°C			30	mV
		V_S = 5.5 V, R_L = 10 k Ω to GND, V_{SENSE} = 0 mV, V_{REF1} = V_{REF2} = 0 V		3	15	mV
V _{OL}	Output Swing from GND	$V_S=5.5~V,~R_L=10~k\Omega~to~GND~,$ $V_{SENSE}=0~mV,~V_{REF1}=V_{REF2}=0~V,$ $T_A=-40^{\circ}C~to~125^{\circ}C$			20	mV
Reference	e Input					
	Reference Input Range		0		Vs	V
	$V_S = 5.5 \text{ V}, V_{REF1} = V_{REF2} = 0.5 \text{ V}$ to $(V_S - 0.5 \text{ V})$ TPA133A0		10		uV/V	
	Reference Voltage Rejection Ratio	$V_S = 5.5 \text{ V}, V_{REF1} = V_{REF2} = 0.5 \text{ V} \text{ to}$ ($V_S - 0.5 \text{ V}$) TPA133A1		6		uV/V
RVRR		$V_S = 5.5 \text{ V}, V_{REF1} = V_{REF2} = 0.5 \text{ V}$ to $(V_S - 0.5 \text{ V})$ TPA133A2, TPA133A3		3		uV/V
		$V_S = 5.5 \text{ V}, V_{REF1} = V_{REF2} = 0.5 \text{ V} \text{ to}$ ($V_S - 0.5 \text{ V}$) TPA133A4		2		uV/V
		$V_S = 5.5 \text{ V}, V_{REF1} = V_{REF2} = 0.5 \text{ V} \text{ to}$ ($V_S - 0.5 \text{ V}$) TPA133A5		1		uV/V
		V _S = 5.5 V, V _{CM} = 95 V, V _{SENSE} = 0 mV, V _{OUT1} : V _{REF1} = GND, V _{REF2} = V _S , V _{OUT2} : V _{REF1} = V _S , V _{REF2} = GND, R _{DA} = (V _{OUT1} - V _{OUT2}) / (V _{OUT1} / 2 + V _{OUT2} / 2), T _A = -40°C to 125°C TPA133A0, TPA133A1, TPA133A2		±0.01	±0.12	%
RDA Reference Divide Accu	Reference Divide Accuracy	Vs = 5.5 V, V _{CM} = 95 V, V _{SENSE} = 0 mV, V _{OUT1} : V _{REF1} = GND, V _{REF2} = V _S , V _{OUT2} : V _{REF1} = V _S , V _{REF2} = GND, R _{DA} = (V _{OUT1} - V _{OUT2}) / (V _{OUT1} / 2 + V _{OUT2} / 2), T _A = -40°C to 125°C TPA133A5		±0.02	±0.25	%
Frequenc	y Response					
BW	Bandwidth	TPA133A0, TPA133A1, TPA133A2, TPA133A3, TPA133A4		1		MHz
		TPA133A5		0.5		MHz

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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
SR Slew Rate	Slew Rate	TPA133A0, TPA133A1, TPA133A2, TPA133A3, TPA133A4		11.5		V/µs
	TPA133A5		8.5		V/µs	
Power Su	pply					
Vs	Supply Voltage	T _A = -40°C to 125°C	3.0		5.5	V
		V _S = 3.0 V		2.5	3	mA
		V _S = 3.0 V, T _A = -40°C to 125°C			3.1	mA
IQ	Quiescent Current	V _S = 5.5 V		2.9	3.7	mA
		V _S = 5.5 V, T _A = -40°C to 125°C			4	mA
PSRR	Power Supply Rejection Ratio	3.0 V < V _S < 5.5 V, T _A = -40°C to 125°C	80	90		dB

⁽¹⁾ To keep the device safe, the common-mode voltage at both V_{IN+} and V_{IN-} must not exceed the survival common-mode input range. To guarantee the specification, common-mode voltage at both V_{IN+} and V_{IN-} should be within the specification common-mode input range.

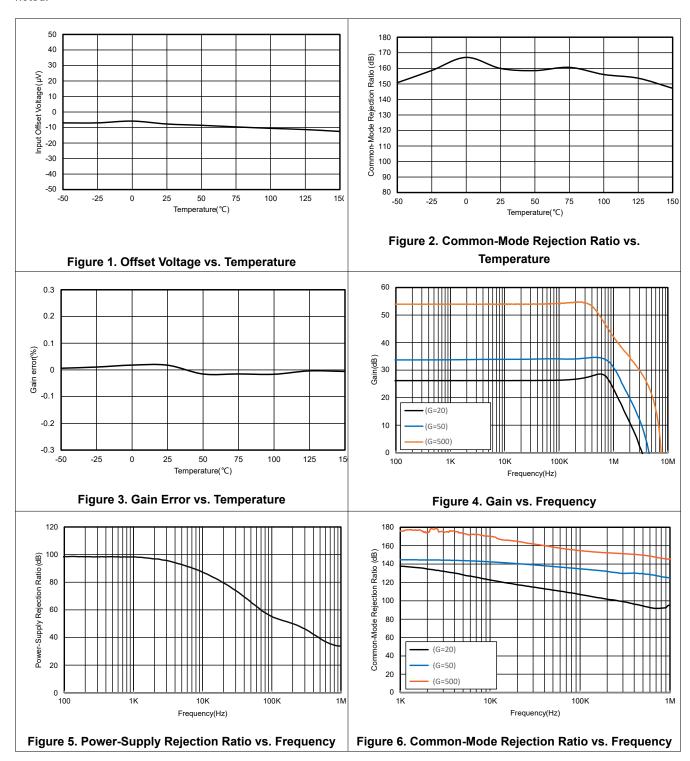
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⁽²⁾ Provided by bench test and design simulation.



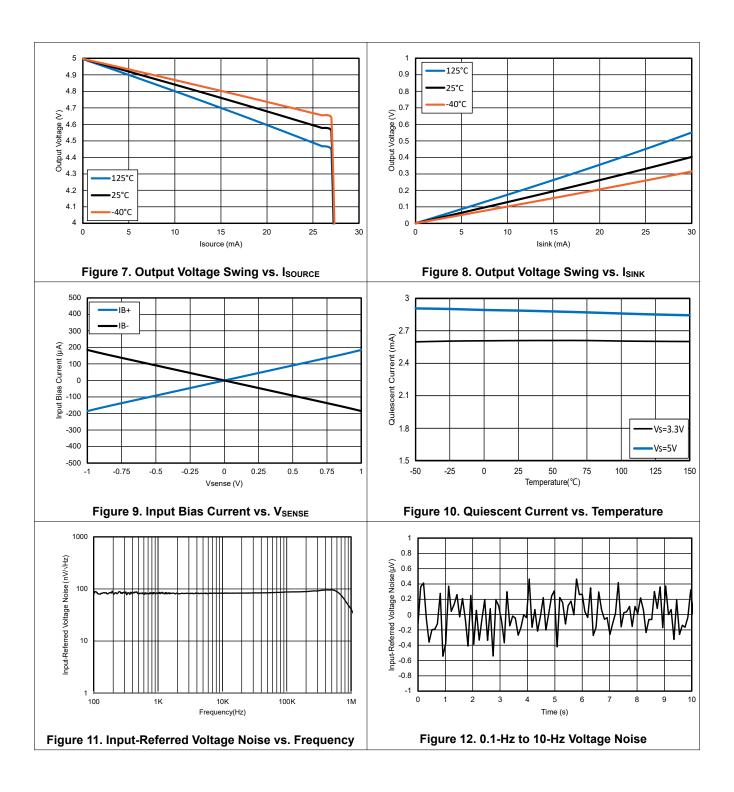
Typical Performance Characteristics

All test conditions: $V_S = 3 \text{ V}$, $TA = 25^{\circ}\text{C}$, $V_{SENSE} = (IN+) - (IN-)$, $V_{CM} = (IN+) = 80 \text{ V}$, $V_{REF1} = V_{REF2} = V_S / 2$, unless otherwise noted.



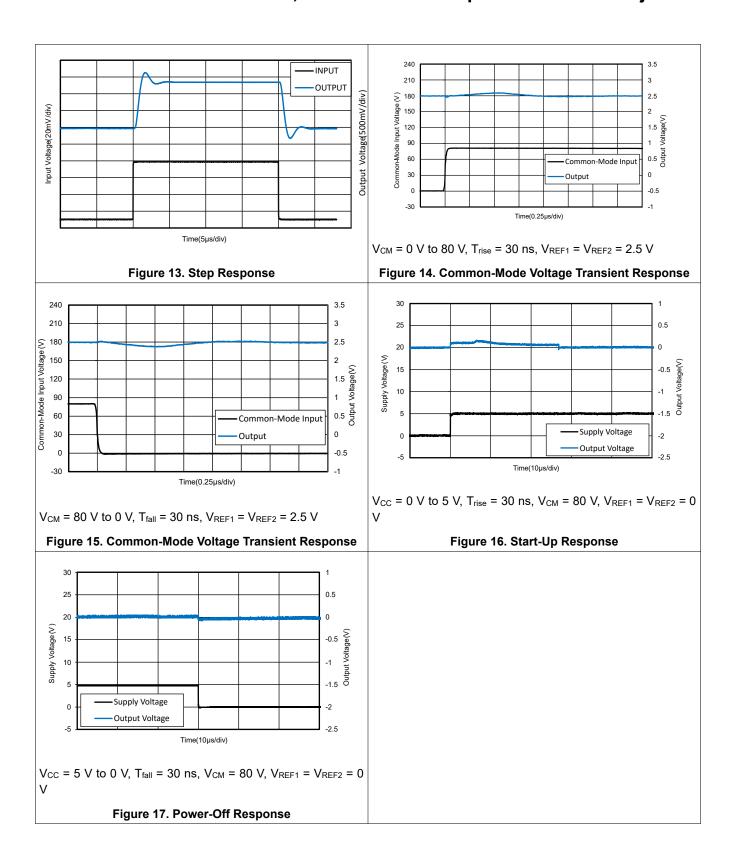
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Detailed Description

Overview

The TPA133 is a high-precision current-sense amplifier with excellent CMRR. Because of its wide input common-mode voltage range, it can be used both in the high-side and low-side current sensing. The TPA133 features enhanced PWM rejection, and it maintains excellent performance even when the input common mode has fast $\Delta V/\Delta t$ transitions. The TPA133 has a bandwidth of up to 1 MHz and an SR of 11.5 $V/\mu s$, which makes it suitable for overcurrent protection and loop control systems that require a fast response speed. The TPA133 boasts exceptional performance in both start-up and power-off scenarios. Its meticulously designed output control mechanisms effectively prevent the system from triggering false alarms and ensure stability and reliability.

Feature Description

Wide Input Common-Mode Voltage Range and Enhanced PWM Rejection

The TPA133 supports a $\neg 4\text{-V}$ to 95-V input common-mode voltage that is independent of the supply voltage (V_S). The ability to operate with common-mode voltages greater or less than V_S allows the TPA133 to be used in both high-side and low-side current-sensing applications.

For a typical solenoid application as shown in Figure 18, when the switch is closed, the common-mode voltage across the R_{sense} swings to the battery voltage (e.g. 48 V). When the switch is open, the common-mode voltage across the R_{sense} reverses to one diode drop below ground (e.g. -0.7 V) due to the recirculation. It brings fast common-mode voltage transitions to the amplifier. The TPA133 provides excellent CMRR and enhances the PWM rejection of this application.

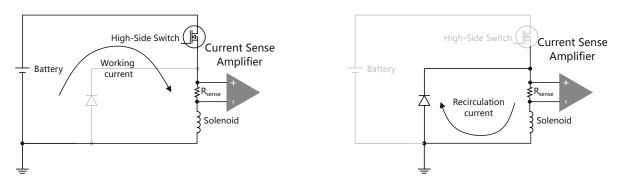


Figure 18. Solenoid Application Circuits

Reference Input, REF

The TPA133 has two reference inputs which range from GND to Vs. It can be used both in unidirectional and bidirectional current sensing operations. The output can be calculated by Equation 1.

$$V_{OUT} = V_{SENSE} \cdot Gain + \frac{V_{REF1} + V_{REF2}}{2}$$
 (1)

For Unidirectional Current Sensing

It is a cost-effective solution to connect both REF1 and REF2 to GND or Vs. However, the current measurement close to 0 is incorrect considering V_{OL}/V_{OH} .

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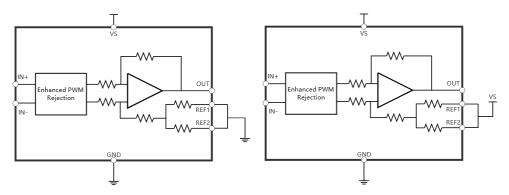


Figure 19. Unidirectional Application Schematic

For Bidirectional Current Sensing

Connecting REF1 to V_S and REF2 to GND is a convenient way to make the output voltage remain $V_S/2$ where there is 0 input. But the output voltage introduces the V_S noise. Connecting REF1 and REF2 to the external reference is a precision but expansive way.

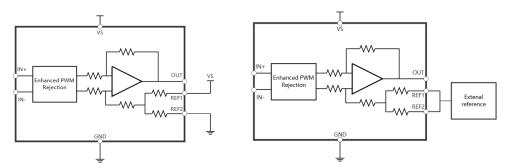


Figure 20. Bidirectional Application Schematic

Excellent start-up and power-off Response

If there is no special treatment, the output of the current-sense amplifier may generate glitches up to the supply voltage during the start-up or power-off of the device. This may cause the system to mistakenly believe that an overcurrent has occurred, leading to fault protection. Using this type of device makes the system more complex and unreliable.

The output of the TPA133 is carefully controlled during its start-up and power-off process to prevent the false triggering of the overcurrent protection, leading to increased reliability and stability. The TPA133 ensures that the output false pulse remains below 700 mV in all scenarios, including:

Various V_{CM} and V_{SENSE}: V_{CM} (common-mode voltage) and V_{SENSE} ((VIN+) - (VIN-)) are set to any voltage allowed in the Electrical Characteristics table (e.g. V_{CM} = 80 V, V_{SENSE} = 50 mV), depending on the application requirements. This enables stable operations regardless of whether the bus voltage in the system is present or not.

Various V_{REF}: Same as V_{CM} and V_{SENSE} , V_{REF} (reference voltage) are set to any voltage allowed in the Electrical Characteristics Tables (e.g. $V_{REF} = 0$ V or 2.5 V), allowing for flexibility in adjusting the sensitivity of the current sensor detection circuit.

Various V_{CC} ramp-up and ramp-down rates: V_{CC} (supply voltage) is ramped up or ramped down at different rates ranging from nanoseconds to milliseconds. This makes the TPA133 suitable for complex industrial scenarios.

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Application and Implementation

Note

Information in the following application sections is not part of the 3PEAK's component specification and 3PEAK does not warrant its accuracy or completeness. 3PEAK's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

Application Information

Selecting the Sense Resistor

The careful selection of an appropriate sense resistor is paramount in achieving accurate and reliable current measurements. To ensure the best performance, it is recommended to carefully evaluate the trade-offs between the resistance value, accuracy, power dissipation, and temperature coefficient.

When selecting a sense resistor, two primary factors should be considered: the desired current measurement range and accuracy, as well as the power dissipation in the resistor. The resistance value and tolerance must be chosen in accordance with the desired current measurement range and the required level of accuracy. Optimizing system performance often involves considering the input voltage across the sense resistor throughout its full dynamic range. However, it is crucial to note that higher resistance values contribute to increased power dissipation, potentially leading to resistor overheating. Moreover, the resistance value may also exhibit drift due to the influence of the temperature coefficient.

Input Filter

The input signal of the TPA133 is sampled by the capacitor with a frequency of about 8 MHz, as shown in Figure 21.

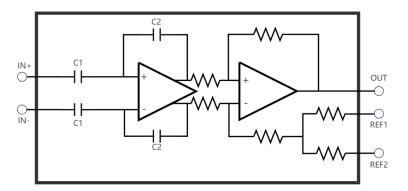


Figure 21. Brief Circuit Diagram of TPA133

According to the Nyquist Sampling Theorem, under-sampling may lead to aliasing. When the noise with a frequency greater than 1/2 * FCLK (4 MHz) is present, it may be aliased to lower frequencies by the sampling structure, interfering with the effective signal.

Therefore, it is highly recommended to include an anti-alias filter at the input of the TPA133. A common first-order RC low-pass filter is shown in Figure 22.

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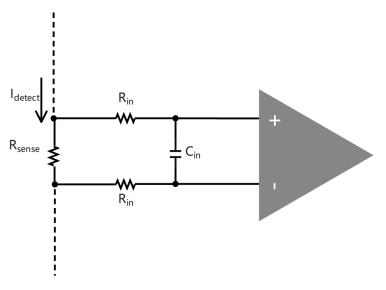


Figure 22. Input Filter Circuit

The bandwidth of the system with filtering can be calculated using Equation 2:

$$BW_{Filter} = \frac{1}{2\pi (2 \cdot R_{in}) C_{in}}$$
 (2)

However, it is crucial to be aware of the potential side effects of input filtering. The input resistance R_{in} plays a role in the voltage division with the chip's differential impedance R_{diff} (5.6 k Ω ±15% for the TPA133), which can introduce an additional gain error:

Gain Error =
$$\frac{2 R_{in}}{2 R_{in} + R_{diff}}$$
 (3)

In general, we have the following suggestions for the input of the TPA133:

- 1. Add an anti-alias low-pass filter with a cutoff frequency equal to or less than the bandwidth of the TPA133 (1 MHz).
- 2. To reduce the gain error, it is recommended that R_{in} is less than or equal to 10 Ω if the system is not calibrated.

Typical Application

Figure 23 shows the typical application schematic.

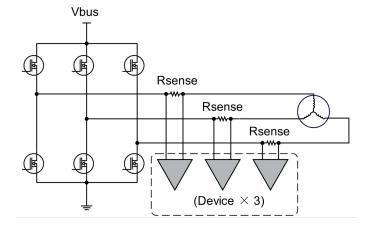


Figure 23. Typical Application Circuit

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Layout

Layout Guideline

- When working with high currents through the R_{SENSE} resistor, it's crucial to minimize the errors caused by the solder and parasitic trace resistance. The four-terminal current sense resistor or the Kelvin (force and sense) PCB layout is recommended to ensure accurate current sensing and optimal performance of the TPA133.
- Ensure that the sense resistor has an ample copper trace area to effectively dissipate heat. This minimizes temperature-induced changes in the value of the resistor and maintains the measurement accuracy.
- Place a 0.1-µF bypass capacitor as close as possible to the supply and ground pins of the TPA133. This minimizes the impact of noise and impedance on the power supply and ensures stable operation.
- Place a low-pass filter as close as possible to the input pins of the TPA133. This effectively avoids aliasing and improves
 measurement accuracy.

Layout Example

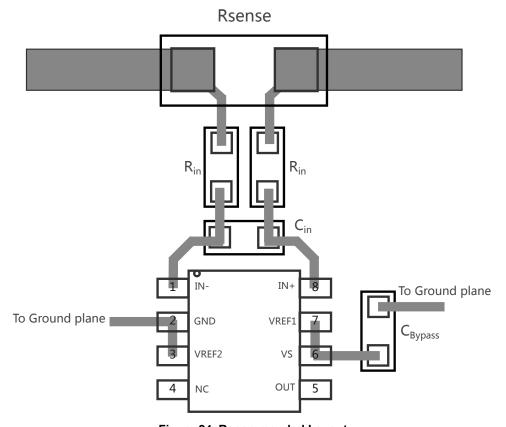
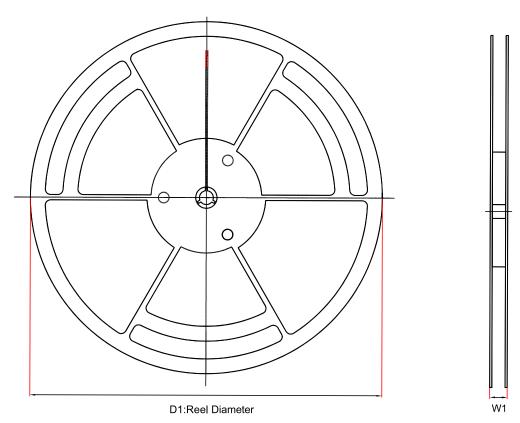


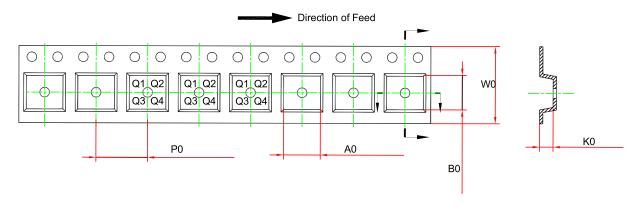
Figure 24. Recommended Layout

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Tape and Reel Information





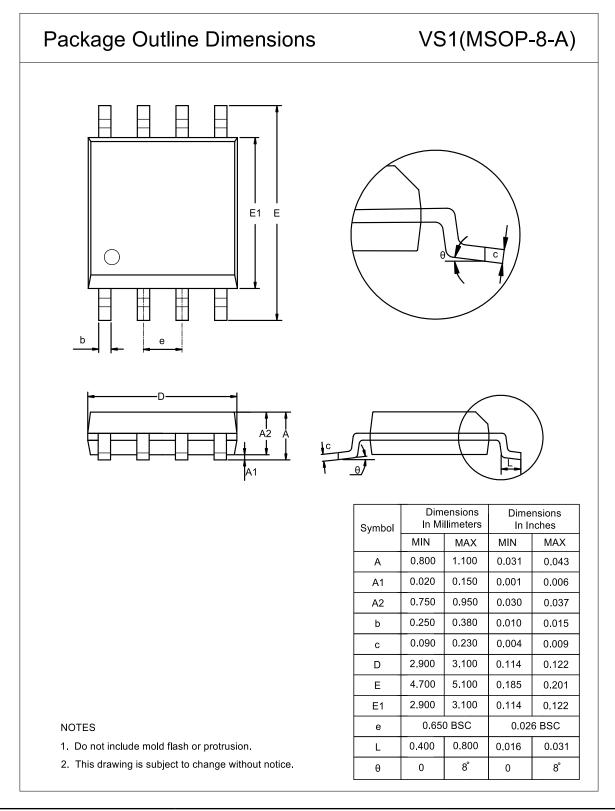
Order Number	Package	D1 (mm)	W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P0 (mm)	W0 (mm)	Pin1 Quadrant
TPA133Ax-VS1R-S	MSOP8	330	17.6	5.3	3.4	1.3	8	12	Q1
TPA133Ax-T8TR-S	SOT23-8	178	13.1	3.3	3.2	1.4	4	8	Q3

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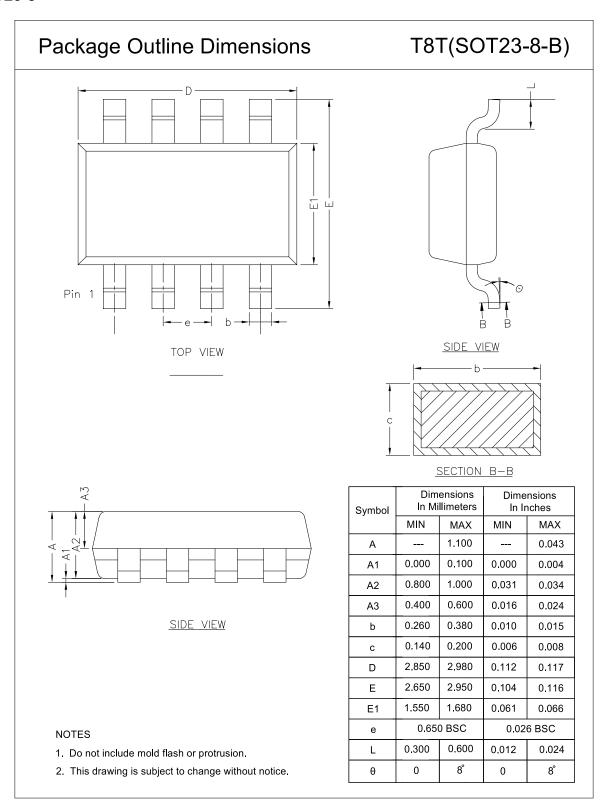
Package Outline Dimensions

MSOP8





SOT23-8



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Order Information

Order Number	Gain	Package	Marking Information	MSL	Transport Media, Quantity	Eco Plan
TPA133A0-VS1R-S	10 V/V	MSOP8	133A0	MSL1	Tape and Reel, 3,000	Green
TPA133A1-VS1R-S (1)	20 V/V	MSOP8	133A1	MSL1	Tape and Reel, 3,000	Green
TPA133A2-VS1R-S (1)	50 V/V	MSOP8	133A2	MSL1	Tape and Reel, 3,000	Green
TPA133A3-VS1R-S (1)	100 V/V	MSOP8	133A3	MSL1	Tape and Reel, 3,000	Green
TPA133A4-VS1R-S (1)	200 V/V	MSOP8	133A4	MSL1	Tape and Reel, 3,000	Green
TPA133A5-VS1R-S (1)	500 V/V	MSOP8	133A5	MSL1	Tape and Reel, 3,000	Green
TPA133A0-T8TR-S (1)	10 V/V	SOT23-8	A9N	MSL3	Tape and Reel, 3,000	Green
TPA133A1-T8TR-S	20 V/V	SOT23-8	A98	MSL3	Tape and Reel, 3,000	Green
TPA133A2-T8TR-S (1)	50 V/V	SOT23-8	A9P	MSL3	Tape and Reel, 3,000	Green
TPA133A3-T8TR-S (1)	100 V/V	SOT23-8	A9M	MSL3	Tape and Reel, 3,000	Green
TPA133A4-T8TR-S (1)	200 V/V	SOT23-8	A9Q	MSL3	Tape and Reel, 3,000	Green
TPA133A5-T8TR-S (1)	500 V/V	SOT23-8	A9R	MSL3	Tape and Reel, 3,000	Green

⁽¹⁾ For future products, contact the 3PEAK factory for more information and samples.

Green: 3PEAK defines "Green" to mean RoHS compatible and free of halogen substances.

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